CHC® M6 GNSS Receiver

Revision 1.0 October 2017



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Safety Warnings

The Global Positioning System (GPS) is operated by the U.S. Government, which is solely responsible for the accuracy and maintenance of the GPS network. Accuracy can also be affected by poor satellite geometry and obstructions, like buildings and heavy canopy.

> M6 GNSS Receiver User Guide Revision 1.0 October 2017

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1. INTRODUCTION

The M6 GNSS Receiver User Guide describes how to set up and use the CHC[®]M6 GNSS receiver.

In this manual, "the receiver" refers to the M6 GNSS receiver unless otherwise stated.

Even if you have used other Global Navigation Satellite Systems (GNSS) products before, CHC recommends that you spend some time reading this manual to learn about the special features of this product. If you are not familiar with GNSS, go to www.chcnav.com for an interactive look at CHC and GNSS.

1.1. SAFETY INFORMATION

1.1.1. WARNINGS AND CAUTIONS

An absence of specific alerts does not mean that there are no safety risks involved.

A Warning or Caution information is intended to minimize the risk of personal injury and/or damage to the equipment.



WARNING - A Warning alerts you to a potential misused or wrong setting of the equipment.



CAUTION - A Caution alerts you to a possible risk of serious injury to your person and/or damage to the equipment.

1.1.2. REGULATIONS AND SAFETY

The receivers contain a built-in wireless modem for signal communication through Bluetooth[®] wireless technology or through external communication datalink. Regulations regarding the use of the wireless modem vary greatly from country to country. In some countries, the unit can be used without obtaining an end-user license. However, in some countries, the administrative permissions are required. For license information, consult your local dealer. Bluetooth[®] operates in license-free bands.

Before operating a M6 GNSS receiver, determine if authorization or a license to operate the unit is required in your country. It is the responsibility of the end-user to obtain an operator's permit or license for the receiver for the location or country of use.

1.1.3. USE AND CARE

This receiver is designed to withstand the rough environment that typically occurs in the field. However, the receiver is high-precision electronic equipment and should be treated with reasonable care.



CAUTION - Operating or storing the receiver outside the specified temperature range will cause irreversible damage.

1.2. TECHNICAL SUPPORT

If you have a problem and cannot find the information you need in this manual or CHC website (www.chcnav.com), contact your local CHC dealer from which you purchased the receiver(s).

If you need to contact CHC technical support, please contact us by email (support@chcnav.com) or Skype (chc_support).

1.3. DISCLAIMER

Before using the receiver, please make sure that you have read and understood this User Guide, as well as the safety information. CHC holds no responsibility for the wrong operation by users and for the losses incurred by the wrong understanding about this User Guide. However, CHC reserves the rights to update and optimize the contents in this guide regularly. Please contact your local CHC dealer for new information.

1.4. YOUR COMMENTS

Your feedback about this user guide will help us to improve it in future revision. Please email your comments to support@chcnav.com.

2. GETTING STARTED WITH M6

2.1. ABOUT THE RECEIVER

The M6 GNSS receiver incorporates a GNSS engine, 3.75G cellular modem, Bluetooth, Wi-Fi, and single-battery in a ruggedized and miniature unit that is easy for you to set up an all-in-one RTK rover or mobile base station. Bluetooth and Wi-Fi technology provide cable-free communication between the receiver and controller.

The receiver can be used as the part of a RTK GNSS system with CHC LansStar7 software. And you can download the GNSS data that recorded in the internal memory of receiver to a computer.

To configure the receiver for performing a wide variety of functions, you can use the web interface by connecting the receiver with PC or smartphone through Wi-Fi.

2.2. PARTS OF THE RECEIVER

The operating controls are all located on the front panel. Battery compartment and SIM card slot are on the bottom. Serial ports and connectors are also located on the bottom of the unit.

2.2.1. FRONT PANEL

The following figure shows a front view of the receiver.



The front panel contains five indicator LEDs, and two buttons.



Name	Description
Power LED(Red)	The indicator to show whether M6 GNSS is on or off.
	• When battery is less than 20% the Power LED will
	flash continuously which reminds you to change the
	battery.
Satellite LED (Green)	Shows the number of satellites that the receiver has tracked.
	• When the receiver is searching satellites, the green LED flashes once every 5 seconds.
	• When the receiver has tracked N satellites, the
	green LED will flash N times every 5 seconds.
Correction LED (Green)	Indicates whether the receiver is transmitting/receiving
	differential data.
	The green LED flashes once per second when
	 As a Base station: successfully transmitting differential data.
	• As a Rover station: successfully receiving differential data from Base station.
Wi-Fi LED (Orange)	Indicates the status of Wi-Fi.
	• When the Wi-Fi LED is orange continuously, Wi-Fi is opening.
Record LED(Yellow)	The record LED only flashes under two situations
	A. In static mode.
	The interval of flashing shows the sample interval of
	collecting data.
	B. RTK mode
	When the receiver is connecting to Controller and
	receiving commands or just communicating with

	Controller.
Switch button	Press Switch button to open or close static mode.
Power button	Turn on or turn off the receiver.
	 Press and hold this button for 3 seconds to turn or or turn off the receiver.

2.2.2. LOWER HOUSING

The lower housing contains one SIM card slot, one battery compartment, one TNC radio antenna connector, two communication and power ports, one 5/8-11 threaded insert, and two nameplates.



2.2.3. RECEIVER PORTS



Port	Name	Description
	IO port	 This port is a 7-pin Lemo connector that supports RS-232 communications and external power input. Users can use GPS to PC Data Cable supplied with the
	USB port	 system to realize RS-232 communications between the receiver and computer or controller. This port is a mini-USB connector that supports USB
		 communications. Users can use USB Cable supplied with the system to download the logged data to a computer.

2.3. BATTERIES AND POWER

2.3.1. INTERNAL BATTERY

The receiver has one rechargeable Lithium-ion battery, which can support for charging.

2.3.1.1. Charging the battery

To charge the battery, first remove the battery from the receiver, and then place it in the battery charger, which is connected to AC power.



WARNING - Charge and use the Lithium-ion battery only in strict accordance with the instructions. Charging or using the battery in unauthorized equipment can cause an explosion or fire, and can result in personal injury and/or equipment damage.

To prevent injury or damage:

• Do not charge or use the battery if it appears to be damaged or leaking.

• Charge the Lithium-ion battery only in a CHC product that is specified to charge it. Be sure to follow all instructions that are provided with the battery charger.

• Discontinue charging a battery that gives off extreme heat or a burning odor.

- Use the battery only in CHC equipment that is specified to use it.
- Use the battery only for its intended use and according to the instructions in the product documentation.

2.3.1.2. Battery safe



WARNING - Do not damage the rechargeable Lithium-ion battery. A damaged battery can cause an explosion or fire, and can result in personal injury and/or property damage.

To prevent injury or damage:

• Do not use or charge the battery if it appears to be damaged. Signs of damage include, but are not limited to, discoloration, warping, and leaking battery fluid.

- Do not expose the battery to fire, high temperature, or direct sunlight.
- Do not immerse the battery in water.
- Do not use or store the battery inside a vehicle under hot weather condition.
- Do not drop or puncture the battery.
- Do not open the battery or short-circuit its contacts.



WARNING - Avoid contact with the rechargeable Lithium-ion battery if it appears to be leaking. Battery fluid is corrosive, and contact with it can result in personal injury and/or property damage.

To prevent injury or damage:

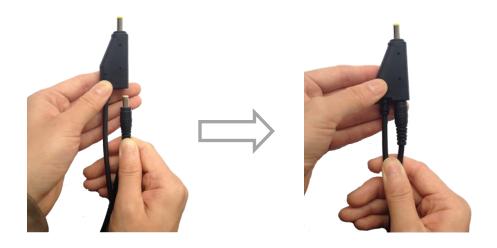
- If the battery leaks, avoid with the battery fluid.
- If battery fluid gets into your eyes, immediately rinses your eyes with clean water and seek medical attention. Please do not rub your eyes!
- If battery fluid gets onto your skin or clothing, immediately use clean water to wash off the battery fluid.

2.3.2. EXTERNAL POWER SUPPLY

Two methods are available for providing the external power to the receiver by the GPS to PC Data Cable+ Power Adapter, or GPS to PC Data Cable + external power cable (option purchase)+ vehicle battery.

In the office:

The Power Adapter is connecting with AC power of 100-240V, the output port of the Power Adapter connects with the Power Port of the GPS to PC Data Cable.



In the field:

The external power cable is connecting with a vehicle battery, the output port of the external power cable connects with the Power Port of the GPS to PC Data Cable.

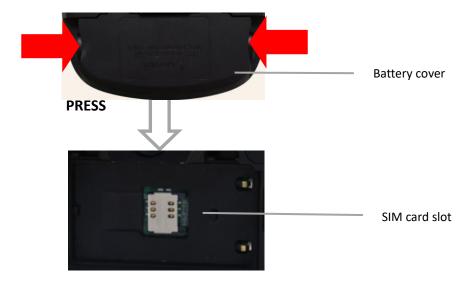


WARNING - Use caution when connecting external power cable's clip leads to a vehicle battery. Do not allow any metal object to connect (short) the battery's positive (+) terminal to either the negative (-) terminal or the metal part of the vehicle battery. This could result in high current, arcing, and high temperatures, exposing the user to possible injury.

2.4. INSERTING BATTERY AND SIM CARD

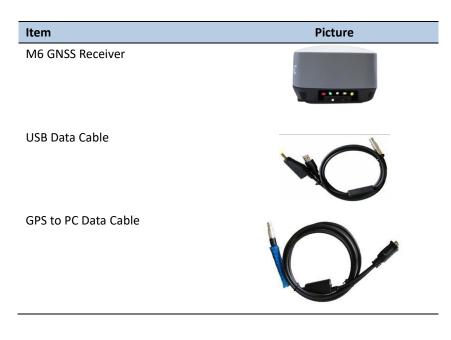
- 1. Press the spring-loaded button on the battery cover to open the cover.
- 2. Insert the SIM card into the SIM card slot.
- 3. To remove the SIM card, take out directly.
- 4. Insert the battery into the battery compartment.

5. To remove the battery, take out directly.



2.5. PRODUCT BASIC SUPPLY ACCESSORIES

2.5.1. BASE KIT BASIC SUPPLY



3. Front panel operation



2.5.2. ROVER KIT BASIC SUPPLY

Item	Picture
M6 GNSS Receiver	
USB Data Cable	NO
GPS to PC Data Cable	
USB2.0 convert to RS232 serial port	
Battery Charger	
External power cable	
Lithium Battery	
2M Range Pole w/bag	
Auxiliary H.I. Tool	•

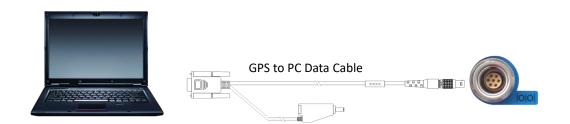
Transport Hard Case



2.6. CONNECTING TO AN OFFICE COMPUTER

The receiver can be connected to an office computer for serial data transfer or settings via a GPS to PC Data Cable. Before you connect to the office computer, ensure that the receiver is powered on by internal battery or external power.

The following figure shows how to connect to the computer for serial data transfer or settings:



2.7. CONNECTING TO A CONTROLLER

2.7.1. CONNECTING VIA WI-FI WITH LANDSTAR 7 SOFTWARE

- 1. Turn on the controller \rightarrow run LandStar 7 \rightarrow go to **Config** main menu \rightarrow tap **Connect**.
- In the *Connect* screen, select CHC for the *Manufacture* field, i80 for Device Type field, Wi-Fi for Connection Type field,

~ •	снс-с	onnect	?
Current Device	Demons	tration:	
Manufacturer	СНС		4
Device Type	i80		
Connection Type	WiFi		
Hot Spot	GNSS-1	002771	((1-
Antenna Type	CHCM6		Ŧ
Auto Connect		No	
Connect to	the Re	ceiver!	
ک ې Discon	nect	@ Co	nnect

Tap the Wireless Lan icon on the right side to select the hot-spot →
 Switch on the Wi-Fi module by the top switch → tap refresh button to search the hot spot around → select the target device in the list.

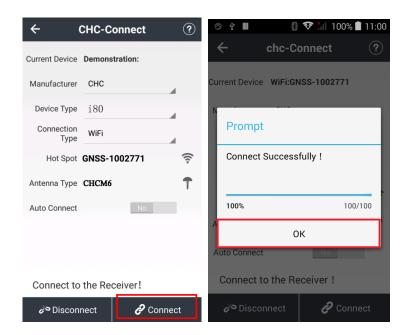
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GNSS-1002771 Saved, secured with WPA/WPA2	(j)
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GNSS-2001530 Secured with WPA/WPA2	A
GNSS-2001527 Secured with WPA/WPA2	
GNSS-7742134 Secured with WPA/WPA2	
() +	:

4. Tap **Connect** to link to the hot spot. If the first-time connection to this hot spot, user may type in the password.



Tip – The Wi-Fi key of the receiver is 12345678 by default.

5. Tap the **Connect** button to build the connection.



2.7.2. CONNECTING VIA BLUETOOTH WITH LANDSTAR 7 SOFTWARE

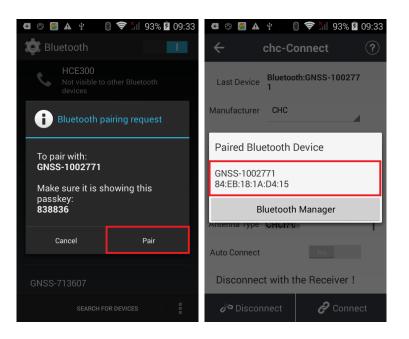
- 1. Turn on the controller \rightarrow run LandStar 7 \rightarrow go to **Config** main menu \rightarrow tap **Connect**.
- In the *Connect* screen, select CHC for the *Manufacture* field, M6 for Device Type field, Bluetooth for Connection Type field.

← (снс-с	onnect		?
Current Device	Demons	tration:		
Manufacturer	СНС			
Device Type	i80			
Connection Type	Bluetoo	oth		
Hot Spot	GNSS-1	002771		*
Antenna Type	CHCM6			Ť
Auto Connect		No		
Connect to	the Red	ceiver!		
ہ ⊃ Discon	nect	Ð	Connec	ct

 Tap the Bluetooth Manager and turn on the Bluetooth function to search bluetooth device around → select the target device in the list.

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← 2017	0904-2-Connect	?	🛨 😌 鬖	▲ ‡	8 🗢 11	93%	≇ 09:33
			💢 Blu	etooth			
Last Device				HCE300			
Manufacturer	СНС	4	~	Not visible devices	to other Blue	etooth	
Device Type	i80		AVAILAB	LE DEVICES			
Connection	Bluetooth	1	GNSS-	1002771			
Paired Bl	uetooth Device	2					
BI	uetooth Manager			GNSS-20	01530		
Auto Connect	No		88:0F:1	0:FC:A8:1	A		
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Disconnect	with the Receiver!						
🖉 Disconr	nect 🕜 Conne	ect	GNSS-	713607			
Ø	0			SEARCI	H FOR DEVICES		ŧ

 Tap Pair to connect the bluetooth device → selected the target device in the bluetooth manager list.



5. Tap the **Connect** button to build the connection.

÷	CHC-Connect	?	🕂 😌 🛃 🗚	Ŷ	§ \$ ¥∥ 9	3% 🛿 09:34
Current Device	Demonstration:		÷	chc-Co	onnect	?
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2.8. DOWNLOADING LOGGED DATA

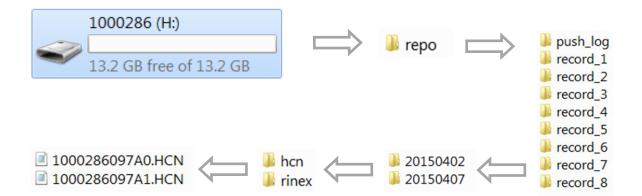
Data logging involves the collection of GNSS measurement data over a period at a static point or points, and subsequent postprocessing of the information to accurately compute baseline information. Data logging using receivers requires access to suitable GNSS postprocessing software such as the CHC Geomatics Office (CGO) Software.

The procedures of downloading logged data in the receiver are as follows:

1. Switch on the receiver and connect it with a computer by USB Cable.

After the successful connection, a removable disk named as the Serial Number (SN) of the receiver will appear on the computer.

- Double click the removable disk and you will see the folder named as "repo". Double click this folder, you will see 9 folders. The "push_log" folder is used to save the log files, and the other 8 folders represent different logging session and are used for store static data.
- Double click the folder that you have configured to store the static data, you will see the folder(s) created by the M6 system automatically and named by the date which is decide by GPS time when you start to log data.
- 4. Select the destination folder and double click it, and then two folders named as different data format (HCN and RINEX) will be displayed.
- 5. Select the data format that you have configured to save the static data, you will find the static raw data.



Tip – For HCN files, the name of the file is represented as XXXXXXDDDNN, where XXXXXX is the SN of the receiver, DDD is day of year, and NN is the recording session.



WARNING – The static data will be saved in the first logging session, the "record_1" folder, by default. Old files will be deleted if the storage space is full. If you configure not to auto delete old files when the memory is low, the receiver will stop data logging.

3. BASE STATION SETUP AND OPERATION

Real-Time Kinematic (RTK) operation provides centimeter-level precision by eliminating errors that are present in the GNSS system. For all RTK operations, you require both a rover receiver and a source of corrections from a base station or network of base stations.

A base station consists of a receiver that is placed at a known point. The receiver tracks the same satellites that are being tracked by the rover receiver simultaneously. Errors in the GNSS system are monitored at the base station, and a series of position corrections are computed. The messages are sent through a radio link to the rover receiver, where they are used to correct the real-time positions of the rover.

This chapter provides the information to help you identify good setup locations, outlines basic precautions that you need to take to protect the equipment, and describes the conventional process to set up the base station and the configuring procedure that required for transmitting correction data.

3.1. BASE STATION SETUP GUIDELINES

For good performance, the following base station setup guidelines are recommended:

- Place the GNSS receiver in a location on the worksite where equal range in all directions provides full coverage of the site.
- Place the GNSS antenna in a location that has a clear line of sight to the sky in all directions. Do not place the antenna near vertical obstructions such as buildings, deep cuttings, site vehicles, towers, or tree canopy.
- The GNSS antenna must have a dear line of sight to the sky always during operation.
- Make sure that the GNSS receiver does not lose power. To operate continuously for more than a few hours without loss of power at the base station, provide external power. When you use an external power supply, the integrated battery provides a backup power supply, enabling you to maintain continuous operation through a mains power failure.
- Do not locate a GNSS receiver, GNSS antenna within 400 meters (about 1,300 feet) of transmitters, such as a power radar or cellular communications tower.
- Do not set up the base station close to the sources of electromagnetic interference, include alternators and generators, electric motors, equipment with DC-to-AC converters, etc.
- Do not operate the receiver outside the specified operating

temperature range -40°C to +60°C (-40°F to +140°F).

 Take reasonable care to keep the GNSS receiver equipment dry, which could prolong their life and reduce the effects of corrosion on ports and connectors.

3.2. OUTPUTTING CORRECTIONS USING EXTERNAL RADIO AND

NETWORK

For External Radio Mode

For base receiver part:

- 1. Screw the M6 receiver onto extension pole.
- 2. Screw the extension pole with auxiliary H.I. tool onto tribrach adaptor.
- 3. Mount the tribrach onto the tripod.
- 4. Insert the tribrach adaptor into the tribrach.
- 5. Level and plumb the receiver over the known (control) point.
- 6. Measure the height of the base station GNSS antenna by measuring the slant height from the known (control) point to the auxiliary H.I. tool.

Note – After entered the vertical height from the known (control) point to the bottom of receiver that you calculated by adding the height of the extension pole to the height from the known (control) point to the end of auxiliary H.I. tool, LandStar 7 will calculate the height to the Antenna Phase Center (APC) automatically.

7. If required, connect the receiver to an external 12 V power supply.

For external radio part (take the CHC DL6 Datalink for example):

- Connect the Datalink Antenna to the 3-meter Cable for Datalink Antenna.
- 9. Connect 3-meter Cable for Datalink Antenna to Datalink Antenna Mounting Pole.
- 10. Screw the Datalink Antenna Mounting Pole onto the tribrach adapter.
- 11. Mount the tribrach onto the tripod.
- 12. Insert the tribrach adaptor into the tribrach.
- 13. Set up the Datalink Antenna nearby the base receiver.
- 14. Fix the DL6 Datalink onto the tripod.
- 15. Place the car battery at an appropriate location.

For connection between the receiver part and external radio part:

- 16. Connect Datalink Antenna to the Datalink Antenna Slot of DL6 Datalink via 3-meter Cable for Datalink Antenna.
- 17. Connect the base receiver with DL6 Datalink via GPS to Datalink Cable.
- 18. Connect the car battery with DL6 Datalink via Datalink External Power Cable.



CAUTION – The Datalink Antenna must be connected to the Datalink before the Datalink is powered on; otherwise, the Datalink can be damaged.



For Network Mode

- 1. Insert the SIM card into M6 GNSS receiver.
- 2. Screw the M6 receiver onto extension pole.
- 3. Screw the extension pole with auxiliary H.I. tool onto tribrach adaptor.
- 4. Mount the tribrach onto the tripod.
- 5. Insert the tribrach adaptor into the tribrach.
- 6. Level and plumb the receiver over the known (control) point.

7. Measure the height of the base station GNSS antenna by measuring the slant height from the known (control) point to the auxiliary H.I. tool.



4. ROVER STATION SETUP AND OPERATION

Real-Time Kinematic (RTK) operation provides centimeter-level precision by eliminating errors that are present in the GNSS system. For all RTK operations, you require both a rover receiver and a source of corrections from network of base stations.

The second part of the RTK GNSS system is the rover receiver. The rover receiver is moved between the points that require measurement or stakeout. The rover receiver is connected to a source of RTK corrections such as a CORS (Continuous Operational Reference System) or the CHC APIS service. The connection is provided by:

- an integrated cellular modem
- a cellular modem in the controller

This chapter provides the information to help you identify good setup locations, describes the conventional process to set up the rover station and the configuring procedure that required for receiving correction data.

4.1. ROVER STATION SETUP GUIDELINES

For good rover operation, observe the following setup guidelines:

 Place the GNSS antenna in a location that has a clear line of sight to the sky in all directions. Do not place the antenna near vertical obstructions such as buildings, deep cuttings, site vehicles, towers, or tree canopy. GNSS rovers and the base station receive the same satellite signals from the same satellites. The system needs five common satellites to provide RTK positioning.



WARNING – Take care not to touch overhead power lines with the CHC M6 GNSS receiver or the range pole when moving the equipment into position. Touching overhead power lines may cause electrocution, leading to serious injury.

- GNSS satellites are constantly moving. Because you cannot measure at a specific location now does not mean that you will not be able to measure there later, when satellite coverage at the location improves.
- To get a fixed position solution with centimeter precision, initialize the RTK rover receiver. For initialization to take place, the receiver must track at least five satellites that the base station is also tracking. In a dual-satellite constellation operation, for example, GPS and GLONASS, the receiver must track at least six satellites.
- To continue to survey at centimeter precision, the rover must

continuously track at least four satellites that the base station is also tracking.

 Loss of the satellite signals will result in a loss of centimeter position precision.

4.2. ROVER STATION SETUP

- 1. Screw the receiver on top of the range pole.
- 2. Fix the controller bracket on the range pole.
- 3. Fit the controller in the controller bracket.
- 4. Level and plumb the receiver over the target measuring point.



5. CONFIGURING THROUGH A WEB BROWSER

Supported browsers:

- Google Chrome
- Microsoft Internet Explorer[®] version 10, or higher

To connect to the receiver through a web browser:

- 1. Turn on the Wi-Fi of the receiver.
- 2. Search the wireless network named as GNSS-XXXXXXX (the SN of your receiver) on your computer, and then establish the connection.
- After the successful connection between your computer and the receiver, enter the IP address of the receiver into the address bar of the web browser on your computer:

192.168.1.	1/pc/login.htr ×
$\leftrightarrow \rightarrow \mathbf{G}$	192.168.1.1/pc/login.html

4. The web browser prompts you to enter a login account and password:

GNSS	
Login Account:	
Password:	
remember me	Login
Please Use Chrome, IE	10+ or Safari to Open

The default login account for the receiver is:

- Login Account: admin
- Password: password

Note – Tick **remember me** option, and then the browser will remember the Login Account and Password you entered for the next time you enter this login screen.

5. Once you are logged in, the web page appears as follows:

🕼 СНС				Quit. English
Status N Satellites N	Receiver Summary			
Rociera Configuration Description Rociera Configuration Rociera Rome R	Receiver Info: Anterna Type: Anterna Type: Meteona Hospit: Elevation Mask: POOP Mask:	1021471 Antenna Phase Center 2.0000(skeler) 20	0101.000000001(South) 0101.000000001(West)	
Data Recording A 1/O Settings B Network Setting A				
tadale Setting R Immune R Joad Service Setting R				

This web page shows the configuration menus on the left of the browser window, and the setting on the right. Each configuration menu contains the related submenus to configure the receiver and monitor receiver performance.

This chapter describes each configuration menu.

To view the web page in another language, select the corresponding language name from the dropdown list on the upper right corner of the web page.

Currently, three languages are available:

English	~
中文	
English	
Русский язык	

5.1. STATUS MENU

This menu provides a quick link to review the receiver's position information, satellites tracked, runtime, current data log status, current outputs, available memory, and more.

Status	
Dosition	
Activity	
🖺 Google Map	

5.1.1. POSITION SUBMENU

This page shows the relevant position information about the receiver's position solution which including the position, DOP values, satellites used

and tracked, and the receiver clock information.

sition			
Position		DOP	
Latitude:	31°9'58.72613874"(North)	PDOP:	1.220000
Longitude:	121°17'18.99714793"(East)	HDOP:	0.682000
Height:	28.304	VDOP:	1.011571
Туре:	3D	TDOP:	0.713000
Satellite Used: 21Tota	d	Satellites Tracked: 21	Total
GPS(8):	1,7,8,9,11,16,27,30	GPS(8):	1,7,8,9,11,16,27,30
GLONASS(6):	9,10,11,19,20,21	GLONASS(6):	9,10,11,19,20,21
BDS(7):	1,2,3,7,8,10,13	BDS(7):	1,2,3,7,8,10,13
GALILEO(0):		GALILEO(0):	
SBAS(0):		SBAS(0):	
Receiver Clock			
GPS Week:	1948		

5.1.2. ACTIVITY SUBMENU

Lists several important items to help you understand how the receiver is being used and its current operating condition. Items include the identities of currently tracked satellites, internal and external storage usage rate, how long the receiver has been operational, state of the internal battery, power source state, files being logged, and data streams being output. With this information, it is easy to tell exactly what functions the receiver is performing:

tellites Track: 20Tota	i i i i i i i i i i i i i i i i i i i	4	Activity Status		
GPS(8): 1	1,7,8,9,11,16,27,30		Current Time:	2017-05-11 07:02	:49 (UTC)
GLONASS(6): 9	10,11,19,20,21		Operation Duration:	00-00-00 00:21:0	4
	2,3,7,8,10,13		Internal Storage:	0.68%	202MB/29728MB
GALILEO(0):			External Storage:	0%	Disconnected
SBAS(0):			External Power:		
			Battery A:	0%	
			Battery B:	0%	
oata Log					
Recording Number	File Name	Activated	Log Status		
1	recordl	No	Inactive		
2	record2 record3	No No	Inactive		
4	record3	Bo	Inactive		
4 5	records	Bo	Inactive		
6	recordo	No	Inactive		
7	recordo	Bo	Inactive		
8	records	No	Inactive		
	1600100	ШŬ	Inscerve		
	records	Bo	Insctive		
0					
° Data Export					
Data Export Port Type		Output Data			
Data Export Port Type 1 NTE Client		Output Data			
Data Export Port Type 1 RTK Client 2 TCF/UDP_Clientl/Htrip					
Data Export Port Type 1 STR Client 2 TCF/UP_Client/Http 3 TCF/UP_Client2/Http	4				
Data Export Port Type 1 KTC Client 2 TCP/UP_Client/Mrtip 4 TCP/UP_Client3/Mrtip	4 5				
Data Export Port Type 1 MTK Cliant 2 TCF/UB_Clientl/Hrip 3 TCF/UB_Clientl/Mrip 5 TCF/UB_Clientl/Hrip	e e	- 			
Data Export Port Type 1 STC Tiant 2 TCF/UB_Cleatl/Heip 3 TCF/UB_Cleatl/Heip 5 TCF/UB_Cleatl/Heip 6 TCF/UB_Cleatl/Heip	4 5 5				
Part Type Fort Type KTK Client TCFV00_Client/Mrtip TCFV00_Client/Mrtip TCFV00_Client/Mrtip TCFV00_Client/Mrtip TCFV00_Client/Mrtip TCFV00_Client/Mrtip	9 0 0 0 0				
Data Export Part Typs 1 2 107/00% Client///wrip 3 177/00% Client///wrip 4 177/00% Client///wrip 5 177/00% Client///wrip 6 177/00% Client///wrip 7 177/00% Client///wrip 6 170% Client///wrip 8 17 172/00% Client///wrip 8 17	4 5 5 5 6				
Data Export Fort Type WT Client 2 707/00_Client//forig 3 TO/00_Client//forig 4 TO/00_Client//forig 5 TO/00_Client//forig 6 TO/00_Client//forig 7 TO/00_Client//Forig 0 TO Surver//TUT Cest 0 TO Surver//TUT Cest	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2				
Data Export Fort Type 1 TGT/BE_Class1/Brig 2 TGT/BE_Class1/Brig 3 TGT/BE_Class1/Brig 4 TGT/BE_Class1/Brig 5 TGT/BE_Class1/Brig 6 TGT/BE_Class1/Brig 7 TGT/BE_Class1/Brig 8 TGT/BE_Class1/Brig 9 TG Server/BELT Cast 9 TG Server/BELT Cast	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2				
Data Export Pert Type 1 NT Client 1 TO/MP_Client/Merg 2 TO/MP_Client/Merg 3 TO/MP_Client/Merg 4 TO/MP_Client/Merg 5 TO/MP_Client/Merg 6 TO/MP_Client/Merg 7 TO/MP_Client/Merg 9 TO Server/MILD Cett 10 TO Server/MILD Cett 10 TO Server/MILD Cett	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2				
Data Export Pert Type WT Client 2 107/WE Client/Heig 3 TO/WE Client/Heig 4 TO/WE Client/Heig 5 TO/WE Client/Heig 6 TO/WE Client/Heig 6 TO/WE Client/Heig 107 Server/HEID Cast 9 TO Server/HEID Cast 10 TO Server/HEID Cast 11 TO Server/HEID Cast 12 Serial Fart	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2				
Data Export Pert Type 1 NT Client 1 TO/MP_Client/Merg 2 TO/MP_Client/Merg 3 TO/MP_Client/Merg 4 TO/MP_Client/Merg 5 TO/MP_Client/Merg 6 TO/MP_Client/Merg 7 TO/MP_Client/Merg 9 TO Server/MILD Cett 10 TO Server/MILD Cett 10 TO Server/MILD Cett	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2				

5.1.3. GOOGLE MAP SUBMENU

Tap this submenu to show the location of the receiver on Google map.



5.2. SATELLITES MENU

Use the Satellites menu to view satellite tracking details and enable/disable GPS, SBAS, GLONASS, BDS and Galileo constellations. These menus include tabular and graphical displays to provide all required information on satellite tracking status.



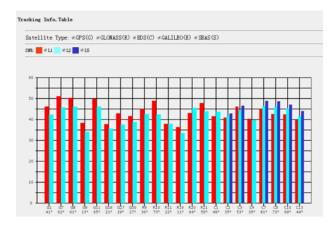
5.2.1. TRACKING TABLE SUBMENU

Provides the status of satellites tracked in general, such as the satellite ID, satellite type, attitude angle, azimuth angle, L1 SNR, L2 SNR, L5 SNR and enable/disable status of each one.

✓ GES	ASS 🗹 BOS 🗹 GALILEO 🗸	SBAS					
SV	Type	Elevation Angle	Azimuth Angle	L1 SNR	L2 598	15 S#8	Inabled
39	19994 GPS	40	ADDULA ADDIA	43.224	30.502	0.000	Tes
7	GPS	40	291	50.767	42.422	0.000	Tes
8	ors GPS	62	291	50.687	42. 422	0.000	Tes
9	GPS	14	234	39.879	43.167	0.000	
							Tes
11	GPS	64	202	50.450	42. 431	0.000	Tes
16	GPS	21	92	38.483	30.539	0.000	Tes
27	GPS	30	44	45.052	33.664	0.000	Tes
30	GPS	25	315	43.215	32.081	0.000	Tes
9	GLOBASS	37	132	43.719	45.671	0.000	Tes
10	GLOBASS	72	9	48.961	44.604	0.000	Tes
11	GLOBASS	22	329	39.839	41.404	0.000	Tes
19	GLOBASS	12	31	33.631	37.786	0.000	Tes
20	GLOBASS	64	4	41.431	48.110	0.000	Tes
21	GLOBASS	50	235	45.855	46.211	0.000	Tes
2	HIS	35	235	37.007	40.947	41.625	Tes
3	HIS	53	200	42.463	43.531	45.378	Tes
4	BES	35	121	32.847	38.553	0.000	Tes
7	IIS	81	92	36.431	45.692	47.898	Tes
8	MS	72	223	37.564	45.705	47.531	Tes
10	IIG	69	325	38, 828	44.253	45.090	Tes
10	105	44	221	37.359	40.187	42.245	Tes

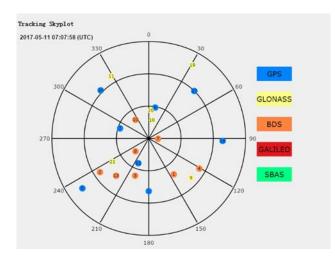
5.2.2. TRACKING INFO. TABLE SUBMENU

The following figure is an example of satellite track diagram page. Users can determine the satellite types and the corresponding SNR of L-band carriers to be displayed in any combination.



5.2.3. TRACKING SKYPLOT SUBMENU

The following figure is an example of Skyplot page.



5.2.4. SATELLITE ACTIVATION SUBMENU

Use this menu to enable or disable satellites.

GPS	GLOB	ASS	BBS	GALILEO	S
E	nable	All	Dist	able All	
Satel	lite	Id Ens	bleSa	tellite Id	Enable
	1	100		2	8
	3	100		4	98
		100		8	10
	7	10		8	
	9	8		10	10
	11	8		12	10
	13	8		14	
	15	10		16	18
	17	8		18	8
	19	100		20	
	21	100		22	8
	23	100		24	8
	25	8		26	8
	27	2		28	8
	29	10		30	8
	31	2		32	

5.3. RECEIVER CONFIGURATION MENU

Use this menu to configure settings such as the antenna type and height, elevation mask and PDOP setting, the reference station coordinates, receiver resetting and web interface language:

Receiver Configuration
Description
Antenna Configuration
Reference Station Settings
🖺 Receiver Reset
🖺 Language
🖺 User Management
🖺 USB Function Switch
HCPPP Settings
1PPS Settings

5.3.1. DESCRIPTION

This submenu shows the receiver information and reference station information, including antenna related information, elevation mask angle, reference station work mode and position, etc.

leceiver Summary			
Receiver Info:		Reference Station Info:	
Antenna Type:	CHOME	Reference Station Mode:	Auto Rover
Antenna Type.	CHCMB	Reference Latitude:	0°0'0.00000000"(South)
Antenna SN:	1021471	Reference Longitude:	0°0'0.00000000"(West)
Measure Way:	Antenna Phase Center	Reference Height:	0.0000
Antenna Height:	2.0000(Meter)		
Elevation Mask:	20		
PDOP Mask:	6		

5.3.2. ANTENNA CONFIGURATION SUBMENU

Use this screen to configure all the items relating to the GNSS antenna. You must enter the correct values for all antenna-related fields, as the choices you make significantly affect the accuracy for logged data and broadcast correction data:

Measure Way:	Antenna Phase Center	~	
Antenna manufacturer:	CHCNav	~	
Antenna Type:	CHCM6	~	
Antenna SN:	1021471]
Antenna Height:	2.0000	_	(Meter)
Elevation Mask:	20]
PDOP Mask:	6		

5.3.3. REFERENCE STATION SETTINGS SUBMENU

Use this screen to configure settings such as the station coordinates and the broadcast station identifiers. You must enter accurate information in these fields, as this data significantly affects the accuracy of logged data files and broadcast correction data:

Reference Station Setting	is .
Reference Station Mode	e: Auto Base 🗸
Base Station Name	e: 1021471
Base Station ID	0: 1021471
Reference Latitude	e: 0 ° 0 ′ 0.0000000 ″ ○N ⊙ S
Reference Longitude	e: 0 ° 0 ′ 0.00000000 ″ ○ E ● W
Reference Height	t: 0.0000
Sample for Average:	
Positioning Constraint:	Single Solution Coordinates O Fixed Solution Coordinates
Sampling Amount: 3	00 🗸 Start 💥 Stop
	0%
	Nave Save

Reference Station Settin	ngs	
Reference Station Mo	de: Auto Rover	~
Sample for Average:		
Positioning Constraint:	Single Solution Coordinates	Fixed Solution Coordinates
Sampling Amount:	300	🖌 Start 🛛 💥 Stop
	0%)
	📑 Save	

Reference Station Settings

Reference Station Mode:	Manual Base	~
Base Station Name:	1021471	
Base Station ID:	1021471	
Reference Latitude:	0 ° 0 ′ 0	" ON 🖲 S
Reference Longitude:	0 0 0	" ○E ●W
Reference Height:	0	
	V Use Current Position	
Sample for Average:		
Positioning Constraint:	Single Solution Coordinates $ \bigcirc $ Fi	ixed Solution Coordinates
Sampling Amount: 300)	🧹 Start 🛛 💥 Stop
	0%	
	Save	
	SAVC	

For Reference Station Mode:

There are three modes available:

- a) Auto Rover: The receiver will serve as a rover after this mode is enabled, and then receive correction data through the working mode set last time.
- b) Auto Base: The receiver will serve as a base after this mode is enabled, and then broadcast correction data based on coordinate inputted by user, or obtained through autonomous positioning automatically.
- c) Manual Base: The receiver will serve neither as a base or a rover after this mode is enabled. Users need to configure the receiver manually.

For Reference Latitude and Reference Longitude:

There are mainly three methods to enter the reference coordinates and shown as follows:

- a) Acquire Current Position: Click this button to acquire current position obtained through autonomous positioning automatically.
- b) Manual Input: Manually input the coordinate of a control point.
- c) From CORS: After the receiver logging in CORS, the software can record the coordinate of current position based on fix solution.

For Sample for Average:

Users can determine the positioning limit and sampling amount. The positioning limit falls into two types:

- Single Solution Coordinates: Collect the coordinates of receiver a) obtained through autonomous positioning.
- b) Fixed Solution Coordinates: Only collect coordinates of receiver with a fixed solution.

After the configuration of positioning limit and sampling amount, click

🖌 Start to carry out sampling and averaging \rightarrow the progress bar will show the progress \rightarrow the result will be served as the coordinate of current position.

If users need to save the changes, please tap button.

5.3.4. RECEIVER RESET SUBMENU

Use this screen to completely or partially reset the receiver:

Receiver Reset	
Reboot Receiver:	V Confirm
Clear Satellite Data:	V Confirm
Reset To Defaults:	V Confirm
Turn Off Receiver:	V Confirm

5.3.5. LANGUAGES SUBMENU

Use this screen to select the web interface language:

Language			
	English	~	V Confirm
	中文		
	English		
	РУССКИЙ		
	Türkçe		
	Español		

5.3.6. USER MANAGEMENT SUBMENU

er Manag	ement		
🕀 Add	ave 🗟	E Delete	V Modify Anti-theft password
ID	User	Name	Password
1	admin		
2	admin	1	
3	admin	2	

5.3.7. USB FUNCTION SWITCH SUBMENU

Use this menu to switch between USB personal area network and Multimedia storage.

USB	Function Switch		
	USB Function Switch:	O USB personal area network	Multimedia storage

5.3.8. HCPPP SETTINGS SUBMENU

Use this menu to select HCPPP Range.

HCPPP Settings		
HCPPP Range:	5min	~
	🗖 Save	

5.3.9. 1PPS SUBMENU

Use this button to turn on or turn off 1PPS.

1PPS Set	tings	
	1PPS Settings:	● ON ○ OFF

5.4. DATA RECORDING MENU

Use the Data Logging menu to set up the receiver to log static GNSS data and to view the logging settings. You can configure settings such as observable rate, recording rate, continuous logging limit, and whether to auto delete old files if memory is low. This menu also provides the controls for the FTP push feature:

Data Recording	- ž
Log Settings	
FTP Push Settings	
FTP Push Log	
🖺 Data Download	

5.4.1. LOG SETTINGS SUBMENU

Here shows the data logging status, including internal and external storage usage and data logging status of each session. Also, users can configure the data logging settings for each session, including recording name, store location, storage limit, store formats, start time, etc.

1 In	Position ernal Storage						
1 In							
			Total Storage	34	orage Available		
			29728MB		29524MB		^
	ernal Storage		OMB		OMB		٣
Recording Numb-	File Name	Activated	Log Status	Setting Parameter	Switch	Clear Data	
Recording Numb-	File Name record1	Activated No.	Log Status Not Recording	Setting Parameter Modify Detail	Switch	Clear Data	
Recording Numb- 1 2							Î
1	record1	¥.	Not Recording	Modify Detail	ONICEE	Clear	Î
1 2	record1 record2	No No	Not Recording Not Recording	Modify Detail Modify Detail	ONICEE	Clear Clear	Î
1 2 3	recordi record2 record3	20 20 20 20	Fot Recording Fot Recording Fot Recording	Hodify Detail Hodify Detail Hodify Detail	ONICEE ONICEE ONICEE	Clear Clear Clear	Î
1 2 3 4	recordi record2 record3 record4	Σο Σο Σο Σο	Yot Recording Yot Recording Yot Recording Yot Recording	Nodifr Detail Nodifr Detail Nodifr Detail Nodifr Detail	ONICEE ONICEE ONICEE ONICEE	Clear Clear Clear Clear	Î
3 4 5	recordi record2 record3 record4 record5	Хо Хо Хо Хо Хо	Sot Recording Sot Recording Sot Recording Sot Recording Sot Recording Sot Recording Sot Recording	Nodify Detail Nodify Detail Nodify Detail Nodify Detail Nodify Detail	ONICEE ONICEE ONICEE ONICEE ONICEE	Clear Clear Clear Clear Clear	

To edit the settings of each session, click the **Modify** button to the right of the required session, and then the *Recording Edit* screen appears:

Recording Edit				×
Auto Record:	⊖Yes ⊙No			
Sample Interval:	5s	~		
Elevation Mask:	20		(°)	
Duration Time:	1440		(Minute)	
Site Name:	1021471]	
Antenna Height:	0.0000]	
Measure Way:	Slant Height	~		
Storage Format:	HCN	~		
RINEX Version:	OFF	×		
	Advance	ed		
	🗖 Save 🍕	B	lack	

Click advanced to see more settings.

	Advanced
Start Date: O Yes	s 🖲 No
Apply Time: O Yes	s 🖲 No
Integral Point Store: O Yes	s 🖲 No
Circulating Memory: Yes	s 🔘 No
	it file after storage space is full
Repeat Observations: • Yes	s 🔘 No
Turn on to record a singl repeated observations.	e observation. Turn off to record
Store Location: Intern	al Storage 🤜
Assigned Storage: 10000) (MB)
Observer: CHC	
Observe Agency: CHC	
FTP Push:	Close 1:ftp server 1 2:ftp server 2 3:ftp server 3

In this screen, you can configure all the data logging parameters, and determine whether the recording files will be affected by the FTP Push. The parameters are mainly as follows:

- File Name: The name of this logging session.
- Sample Interval: Select the observable rate from the dropdown list.
- Store Location: Determine whether to store at internal storage or external storage.
- Enable Start Time: Set the start time of data logging in UTC. Select Or not option below to determine whether to start data logging from the start time defined, or immediately after this session is switched on.
- > **Duration Time**: Set the duration of data logging.
- > Assigned Storage: Set the storage space of this session.
- Circulating Memory: Select Yes or No option to determine whether to auto delete old files if the storage space is full.
- > Data Format: Set the data format of the logged data.
- FTP Push: Decide whether to push the stored files to the FTP server of your choice.

Tap Save button to save the settings and back to the Log Settings

screen. Also, users can click Back to abandon the changed settings and back to Log Settings screen.

Note – To modify data logging parameters, make sure the data logging session is switched off.

To switch on or off **ANY** data logging session, tap the **ON** or **OFF** button to the right of the required session.

To delete the recorded files of **ANY** data logging session, tap the **Clear** button to the right of the required session.

To delete the recorded files of **ALL** data logging sessions, tap the **Clear ALL Accounts** button.

5.4.2. FTP PUSH SETTINGS SUBMENU

Use this screen to configure the receiver to push stored files to the FTP server of your choice. Only files that are configured to use FTP push are transmitted.

Push Settings				
ecord Info				
Server ID	Server IP	Remote Directory	Server Description	Modify
1	192.168.3.72	/repo/first	ftp server 1	Hodify
2	192.168.3.72	/repo/second	ftp server 2	Modify
3	192.168.3.72	/repo/thirdd	ftp server 3	Hodify

Tap **Modify** button to the right of the required FTP server and the *FTP Push Settings* screen appears:

FIP Push Settings	×
Server IP: 192.168.3.72	
Port: 21	
Remote Directory: /repo/first	
Server Description: ftp server 1	
User Name: ftpuser1	
Password: ••••••	
🔂 Save 🛛 🧔 Back	

5.4.3. FTP PUSH LOG SUBMENU

Shows the related information about the recorded filed that be pushed. And users can tap **Clear Ftp Send Log** button in the upper right corner to clear the log of FTP Push operations.

FT	Push Log						
	Record Info						
					Clear FIP Push Log		
	Server ID	Push File	File Size	Push Time	Push Successful Or Not		
	20 • H 4 Page	1 of 1 🕨 🕅 Ö			Displaying 0 to 0 of 0 items		

5.4.4. DATA DOWNLOAD SUBMENU

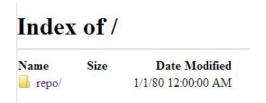
In this submenu, users can download the data files that recorded in the internal storage through the internal FTP site.

1. Click this submenu, and then the log on dialogue box will prompt you to enter a user name and password:

Authentication Required		\times
The server ftp://192.168.1.1:2 password.	21 requires a usern	name and
User Name:		
Password:		
	Log In	Cancel

The default logon account for the internal FTP site is:

- User name: ftp
- Password: ftp
- 2. Click the directory named as "repo" to view and download the files currently stored on the receiver:



To find the file need to be downloaded, click the name of data logging session → the date of file that be recorded → the format of the file → the name of the target file.

Name	Size	Date Modified
1 [parent directory]		
1000514138D.15C	0 B	5/18/15 3:04:00 AM
1000514138D.15G	0 B	5/18/15 3:04:00 AM
1000514138D.15N	0 B	5/18/15 3:04:00 AM
1000514138D.15O	8.0 kB	5/18/15 3:04:00 AM
1000514138F.15C	0 B	5/18/15 5:56:00 AM
1000514138F.15G	0 B	5/18/15 5:56:00 AM
1000514138F.15N	0 B	5/18/15 5:56:00 AM
1000514138F.15O	240 kB	5/18/15 5:59:00 AM
1000514138I.15C	0 B	5/18/15 8:15:00 AM
1000514138I.15G	0 B	5/18/15 8:15:00 AM
🗋 1000514138I.15N	0 B	5/18/15 8:15:00 AM
1000514138I.15O	64.0 kB	5/18/15 8:16:00 AM

Index of /repo/record_1/20150518/rinex/

 To download a file, left-click the name of the target file → download the file according to the prompts.

5.5. IO SETTINGS MENU



Use the IO Settings menu to set up all receiver outputs and inputs. The receiver can output CMR, RTCM, Raw data, Ephemeris data, GPGGA, GPGSV, on TCP/IP, UDP, serial port, or Bluetooth ports.

5.5.1. IO SETTINGS SUBMENU

The following figure shows an example of the screen that appears when you select this submenu.

	Type	Description	Output	Connection Status Modify
1	RTK Client	211.144.118.5:2102		Unconnected Connect Disconnecting De
2	TCP/UDP_Client1/NTRIP Serv	192.168.3.18:9900		Unconnected Connect Disconnecting De
3	TCP/UDP_Client2/NTRIP Serv	192. 168. 3. 18:9901		Unconnected Connect Disconnecting De
4	TCP/UDP_Client3/NTRIP Sert	192.168.3.18:9902		Unconnected Connect Disconnecting De
5	TCP/UDP_Client4/NTRIP Serv	192.168.3.18:9903		Unconnected Connect Disconnecting De
6	TCP/UDP_ClientS/NTRIP Serv	192.168.3.18:9904		Unconnected Connect Disconnecting De
7	TCP/UDP_Client6/NTRIP Sert	192.168.3.18:9905		Unconnected Connect Disconnecting De
8	TCP Server/WIRIP Caster1	9901		Closed Connect Disconnecting De
9	TCP Server/WIRIP Caster2	9902		Closed Connect Disconnecting De
10	TCP Server/WIRIP Caster3	9903		Closed Connect Disconnecting De
11	TCP Server/NTRIP Caster4	9904		Closed Connect Disconnecting De
12	Serial Port	9600		Settings
13	Bluetooth	GMSS-1013103	GPGGA: Ss,	Settings
14	Radio	462. 0500#Hz		Settings
15	GSM	Rover		Offline Settings Connect

In this submenu, users can configure 6 types of input and output settings.

1. RTK Client

After configuring the settings of RTK client, users can log on CORS or APIS. Tap the **Connect** button to the right \rightarrow the *IO Settings* screen will appear \rightarrow choose one of the connection protocols among the NTRIP, APIS_BASE and

APIS_ROVER \rightarrow configure the related parameters \rightarrow click to log on CORS or APIS.

Connection Protocol: NTRIP

Connection Protocol:	NTRIP	
Server IP:	108.171.124.25	
Port:	2103	
Mount Point:	CHC-&-GEC 🗸 🖌 Get	
User Name:	user	
Password:	1234	
	G Confirm 🎯 Back	

Connection Protocol: APIS_BASE

Connection Protocol:	APIS_BASE V	
Server IP:	111.111.111.1	
Port:	9901	
Differential Data:	OFF 🗸	

Connection Protocol: APIS_ROVER

Connection Protocol:	APIS_ROVER V	
Server IP:	210.14.66.58	
Port:	9902	
Base ID:	~	
	Confirm 🎯 Back	

2. TCP/UDP Client

Tap the **Connect** button to the right of required TCP/UDP Client \rightarrow the *IO* Settings screen will appear \rightarrow select the connection protocol between TCP and UDP \rightarrow enter the IP and Port of the target server \rightarrow configure messages

that you want to output to the target server $ o$ click	Confirm	to save
and complete the connection.		

Connection Protocol:	TCP 🗸	
Server IP:	201.255.122.215	
Port:	9902	
	🗖 Confirm 🛭 🞯 Back	

3. TCP Server/NTRIP Caster

Tap the **Connect** button to the right of required TCP Server/NTRIP Caster \rightarrow the **IO Settings** screen will appear \rightarrow select one of the connection protocols between NTRIP and TCP \rightarrow configure the other related parameters \rightarrow click

금 Confirm

to save the settings and open the server.

Connection Protocol: NTRIP

Auto connect:					
Connection Protocol:	NTRIP			~	
User Name:					
Password:					
Port:	9901				
Mount Point:					
Differential Data:	OFF	~			
Raw Data:	OFF	~			
HCPPP Data:	OFF			~	
HRC Data:	OFF			~	
NMEA:	GPGGA	~	OFF	~	
Retransmit:	RTK	~	OFF	~	

\triangleright **Connection Protocol: TCP**

Auto connect:					
Connection Protocol:	TCP			~	
Port:	9901				
Differential Data:	OFF	~			
Raw Data:	OFF	~			
HCPPP Data:	OFF			~	
HRC Data:	OFF			~	
NMEA:	GPGGA	~	OFF	~	
Retransmit:	RTK	~	OFF	~	

4. Serial Port

Tap the **Settings** button to the right of Serial Port \rightarrow the Serial Port Setup screen will appear \rightarrow select Baud Rate used to transmit data \rightarrow configure the messages that you want to output through the serial port $\rightarrow \mbox{click}$



Confirm to save the settings and start to transmit.

Baud Rate:	9600			¥
Differential Data:	OFF	~		
Raw Data:	OFF	~		
HCPPP Data:	OFF			~
HRC Data:	OFF			~
NMEA:	GPGGA	~	OFF	~
Retransmit:	RTK	~	OFF	~

5. Bluetooth

Tap the **Settings** button to the right of Bluetooth \rightarrow the *Bluetooth Set* screen will appear \rightarrow configure the messages that you want to transmit through

Bluetooth \rightarrow click	Confirm	to s	ave the	settings	and start t	o transmit.
	Bluetooth Setti			×		
	Differential Data	OFF	~			
	Raw Data:	OFF	~			
	HCPPP Data	OFF	*			
	HRC Data	OFF	~			

NMEA: GPGGA 🗸 5s 🗸 🔚 Confirm 🛭 🞯 Back

5.6. NETWORK SETTING MENU

Use this menu to view network information, configure the receiver's mobile network, set email alert for specific situation, configure HTTP or HTTPS port, and the user name and password of internal FTP site:

Network Setting	\approx
Description	
Mobile Network Setting	
Email Alarm	
E FTP Service	

5.6.1. DESCRIPTION SUBMENU

Use this submenu to check the information of network setting.



5.6.2. MOBILE NETWORK SETTING SUBMENU

Use this submenu to configure GPRS model, network module and modify dialing status.

Mobile Network Sett	ting
GPRS Model Status:	ON 🔹 ON 😰 OFF
Auto Start:	⊛ Yes ⊙ No
Network Mode:	○ 2G Only ○ 3G Only ⑧ 2G/3G Auto
Dialing Status:	Offline 🔹 Dial 😮 Break
Auto Connect:	⊙Yes ⊛No
GSM:	
APN:	3gnet
Dialing String:	*99# 🗸
User Name:	card
Password:	
	🛃 Save

5.6.3. EMAIL ALARM SUBMENU

Use this submenu to choose which situation of receiver will be alerted and input the email address.

Email Alert Setting	ţs
TO	
Email Address 1:	test@huacenav.com
Email Address 2:	
Email Address 2:	
Linai Address J.	lesiz@nuacenav.com
	🔄 Save
From	
Account:	
Password:	
Server Address:	
	ave Save
Email Alert	
	Receiver is powered on
	External power is off
	Battery level is low
	Ftp push is failed
	Reciever(license) will be expired in 7 days.
	ave

5.6.4. HTTP SUBMENU

Use this submenu to configure HTTP port.

нттр
HTTP Port: 80

5.6.5. HTTPS SUBMENU

Use this submenu to configure HTTPS port.

HTTPS	
	Enable HTTPS: Yes No
	HTTPS Port: 443
	📃 Save

5.6.6. FTP SERVICE SUBMENU

Use this submenu to configure the user name and password of internal FTP site.

FTP Settings	
User Name:	
Password:	•••
	🛃 Save

5.7. MODULE SETTING MENU

Use this menu to check module information, configure Wi-Fi, Bluetooth, radio related settings:

Module Setting	4
🖹 Description	
🗐 WiFi	
📋 Bluetooth Settings	

5.7.1. DESCRIPTION SUBMENU

Use this submenu to check the information of Wi-Fi module, Bluetooth module and radio module.

odule Abstract			
WI-FI Information:		Radio Information:	
Power Status:	ON	Radio Type:	
Wifi Mode:	Access Point	Radio Power:	
MAC:	de:ad:be:02:14:71	OTA Baud Rate:	
Access Point Details		Radio Frequency:	0.0000MHz
SSID:	GNSS-1021471	Radio Protocol:	
Encryption Type:	WAP	Radio Frequency	
Password:	12345678	Channel: Frequency Range:	undefinedMHzundefinedMH

5.7.2. WI-FI SUBMENU

Use this submenu to turn on/off Wi-Fi function and modify password.

Power Status:	ON 🙆 OFF
Auto Start:	●Yes ○No
Internet:	●Yes ○No
Wifi Mode:	Access Point
SSID:	GNSS-1021471
Encryption Type:	WAP 🗸
Password:	•••••

5.7.3. BLUETOOTH SETTINGS SUBMENU

Use this submenu to turn on/off Bluetooth function and modify PIN number.

Bluetooth Settings	
Loodin Hainto.	GNSS-1021471 20:C3:8F:A2:08:40
Visible: PIN:	● Yes ○ No 1234 Save

5.7.4. BUZZER SETTING SUBMENU

Use this submenu to turn on/off static voice.

Buzzer Setting				
Static Voice		0	Off	
	🗟 Save			

5.8. FIRMWARE MENU

Use this menu to check the current firmware information, download the system log, update the receiver firmware, download or update the configuration file and register the receiver, and more:

Firmware	\approx
🖹 Firmware Info.	
🗐 Hardware Version	
🖺 Config File	
🗐 System Log	
🖺 User Log	
🖺 Firmware Update	
🖺 GNSS Board Upgrade	
🖺 Radio Upgrade	
🗎 Upgrade Online	
📋 GNSS Registration	

5.8.1. FIRMWARE INFO SUBMENU

Use this submenu to check the current firmware information. The following figure shows an example of the firmware information.

Firmware Info.	
Firmware Version: Firmware Release Time:	

5.8.2. HARDWARE VERSION

Use this submenu to check the hardware information, including main board version and core board version:

Hardware Version	
Main Board:	1.1
Core Board:	1.4
PN:	1180081035142
Board Firmware Version Number:	5.11

5.8.3. CONFIG FILE

Use this submenu to update Configuration File.

Config File
Download Configuration File : 🛛 💅 Download
Update Configuration File: Browse Confirm

5.8.4. System Log Download Submenu

Use this submenu to download the system log of the receiver.

System Log Download		
System Log Type:	Firmware Log	~
	🎸 Download	

5.8.5. USER LOG

User Log	
Download Use	r Log: 🛛 🖌 Download
User Log settings	
	System Starting Time
	External Power Removed
	Satellites Tracking Status Changed
	TCP Client Connection
	TCP Client Disconnect
	Observation Recording Start and End
	FTP file pushed
	Email alert time
	Wi-Fi Status
	Bluetooth status
	Sensor status
۲	CORS and APIS states
×.	3g Connection status
	🗔 Confirm

5.8.6. FIRMWARE UPDATE SUBMENU

Use this submenu to load new firmware to the receiver across the network. Tap the **Browse** button to locate the upgrade file \rightarrow tap **Confirm** button to confirm the selected upgrading file and start upgrading.

Firmware	Update	
	Upgrade File:	Browse
	[Confirm

Notes

- It may take about 3 or 4 minutes to complete the firmware upgrading. Do not touch the power button or unplug the power until the upgrading process is finished, or damage will be caused to the receiver.
- The receiver will restart after the firmware upgrading is done, so users need to reconnect the receiver with your computer via Wi-Fi, and then log-in the receiver through a web browser to continue the configuration.

5.8.7. GNSS BOARD UPGRADE

Use this submenu to upgrade GNSS Board.

GNSS	Board Upgrade	
	Upgrade File:	Browse
	[Confirm

5.8.8. RADIO UPGRADE

Use this submenu to browse upgrade file and upgrade radio.

F	Radio Upgrade
	Upgrade File: Browse
	Confirm

5.8.9. UPGRADE ONLINE

Use this submenu to input Server Address and upgrade online. ${\tt Upgrade\ Online}$

Server Address: http://clou	d.huacenav.com:6001 (http:	//cloud.huacenav.com:6001)			
	🔜 Save				
					✔ Get File List
File Name	Version	Description	Size	Upgrade	Get File List
		Description	3126		
10 🔻 候 🦿 Page 1 of	1 🕨 🕅 🔿			Displaying	O to O of O items

5.8.10. GNSS REGISTRATION SUBMENU

Use this submenu to register the receiver. Paste or enter the registration code to the *Registration Code* field \rightarrow tap **Registration** button to complete the registration.

SNSS Registration	
Serial Number:	1021471
Registration Limit:	permanent
Registration Code:	41423-31402-29583
	Registration
16 GNSS Receiver User Gu	uide

5.9. CLOUD SERVICE SETTING MENU

5.9.1. CLOUD SERVICE SETTING SUBMENU

Cloud Service Setting
🗐 Cloud Service Setting

Use this submenu to turn on or turn off Cloud Service, Auto Start, Remote Control and configure other settings.

Cloud Service Setting	
Cloud Service States	s ON 🔞 OFF
Auto Start	· ·
Remote Control	
Anti-theft	
	heft mode and the function will uuto on and upload location info! Next On Off
Time Interval	30s 🗸
Position Interval	50Meter 🗸
Address	cloud.huacenav.com
Port	10000
Modify Anti-theft pa	issword 🔂 Save

A. COMMUNICATION PORTS DEFINITION

A.I. CHC M6 RECEIVER IO PORT (7-PIN LEMO PORT) DEFINITION



PIN	FUNCTION
1	Ground (-)
2	Ground (-)
3	RS232-TX (Output)
4	PPS
5	Not Used
6	VIN
7	RS232-RX (Input)

CHC - Shanghai Huace Navigation Technology Ltd. Building C, NO. 599 Gaojing Road, Qingpu District, 201702 Shanghai, China Tel: +86 21 542 60 273 Fax: +86 21 649 50 963 Email: <u>sales@chcnav.com</u> | <u>support@chcnav.com</u>

Website: www.chcnav.com