CHC® i70 GNSS Receiver

Geodesical
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Safety Warnings
The Global Positioning System (GPS) is operated by the U.S. Government, which is solely responsible for the accuracy and maintenance of the GPS network. Accuracy can also be affected by poor satellite geometry and obstructions, like buildings and heavy canopy.
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1. INTRODUCTION

The i70 GNSS Receiver User Guide describes how to set up and use the CHC® i70 GNSS receiver.

In this manual, “the receiver” refers to the i70 GNSS receiver unless otherwise stated.

Even if you have used other Global Navigation Satellite Systems (GNSS) products before, CHC recommends that you spend some time reading this manual to learn about the special features of this product. If you are not familiar with GNSS, go to www.chcnav.com for an interactive look at CHC and GNSS.

1.1. SAFETY INFORMATION

1.1.1. WARNINGS AND CAUTIONS

An absence of specific alerts does not mean that there are no safety risks involved.

A Warning or Caution information is intended to minimize the risk of personal injury and/or damage to the equipment.

WARNING - A Warning alerts you to a potential misused or wrong setting of the equipment.

CAUTION - A Caution alerts you to a possible risk of serious injury to your person and/or damage to the equipment.

1.1.2. REGULATIONS AND SAFETY

The receivers contain a built-in wireless modem for signal communication through Bluetooth® wireless technology or through external communication datalink. Regulations regarding the use of the wireless modem vary greatly from country to country. In some countries, the unit can be used without obtaining an end-user license. However, in some countries, the administrative permissions are required. For license information, consult your local dealer. Bluetooth® operates in license-free bands.

Before operating a i70 GNSS receiver, determine if authorization or a license to operate the unit is required in your country. It is the responsibility of the end-user to obtain an operator's permit or license for the receiver for the location or country of use.
1.1.3. **USE AND CARE**

This receiver is designed to withstand the rough environment that typically occurs in the field. However, the receiver is high-precision electronic equipment and should be treated with reasonable care.

**CAUTION** - Operating or storing the receiver outside the specified temperature range will cause irreversible damage.

1.2. **TECHNICAL SUPPORT**

If you have a problem and cannot find the information you need in this manual or CHC website (www.chcnav.com), contact your local CHC dealer from which you purchased the receiver(s).

If you need to contact CHC technical support, please contact us by email (support@chcnav.com) or Skype (chc_support).

1.3. **DISCLAIMER**

Before using the receiver, please make sure that you have read and understood this User Guide, as well as the safety information. CHC holds no responsibility for the wrong operation by users and for the losses incurred by the wrong understanding about this User Guide. However, CHC reserves the rights to update and optimize the contents in this guide regularly. Please contact your local CHC dealer for new information.

1.4. **YOUR COMMENTS**

Your feedback about this user guide will help us to improve it in future revision. Please email your comments to support@chcnav.com.
2. GETTING STARTED WITH i70

2.1. ABOUT THE RECEIVER

The i70 GNSS receiver incorporates a GNSS engine, GNSS antenna, internal radio, optional 4G cellular modem, Bluetooth, Wi-Fi, and dual-battery in a ruggedized and miniature unit that is easy for you to set up an all-in-one RTK rover or mobile base station.

The LCD panel enables you to check satellite-tracking status, internal battery status, Wi-Fi status, working mode, data logging status and basic receiver information. Bluetooth and Wi-Fi technology provide cable-free communication between the receiver and controller.

The receiver can be used as the part of a RTK GNSS system with CHC LansStar 7 software. And you can download the GNSS data that recorded in the internal memory of receiver to a computer.

You can change basic settings of the receiver with its LCD panel. To configure the receiver for performing a wide variety of functions, you can use the web interface by connecting the receiver with PC or smartphone through Wi-Fi.

2.2. PARTS OF THE RECEIVER

The operating controls are all located on the front panel. Battery compartment and SIM card slot are on the backside. Serial ports and connectors are located on the bottom of the unit.

2.2.1. FRONT PANEL

The following figure shows a front view of the receiver.

The front panel contains one LCD screen, two indicator LEDs, and two buttons.
### Getting started with i70 GNSS Receiver User Guide

#### Name

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Satellite LED (Green)</td>
<td>Shows the number of satellites that the receiver has tracked.</td>
</tr>
<tr>
<td></td>
<td>- When the receiver is searching satellites, the green LED flashes once every 5 seconds.</td>
</tr>
<tr>
<td></td>
<td>- When the receiver has tracked N satellites, the green LED will flash N times every 5 seconds.</td>
</tr>
<tr>
<td>Correction LED (Yellow)</td>
<td>Indicates whether the receiver is transmitting/receiving differential data.</td>
</tr>
<tr>
<td></td>
<td>The yellow LED flashes once per second when</td>
</tr>
<tr>
<td></td>
<td>- As a Base station: successfully transmitting differential data.</td>
</tr>
<tr>
<td></td>
<td>- As a Rover station: successfully receiving differential data from Base station.</td>
</tr>
<tr>
<td>LCD screen</td>
<td>This liquid crystal display enables you view the basic information and current configuration settings of receiver.</td>
</tr>
<tr>
<td>Fn button</td>
<td>- Move to next line of the menus or options.</td>
</tr>
<tr>
<td></td>
<td>- Move to next character of the value that you want to make change.</td>
</tr>
<tr>
<td></td>
<td>- Cancel the change you make on a function.</td>
</tr>
<tr>
<td>Power &amp; Enter button</td>
<td>Works as a Power button:</td>
</tr>
<tr>
<td></td>
<td>- Press and hold this button for 3 seconds to turn on or turn off the receiver.</td>
</tr>
<tr>
<td></td>
<td>Works as an Enter button:</td>
</tr>
<tr>
<td></td>
<td>- Advance to next screen.</td>
</tr>
<tr>
<td></td>
<td>- Make change to the selected character or field.</td>
</tr>
<tr>
<td></td>
<td>- Confirm the change you make on a function.</td>
</tr>
<tr>
<td></td>
<td>- Confirm the changes you make on a screen.</td>
</tr>
</tbody>
</table>
2. Getting started with i70

Works as a Reset button:
- Hold Fn button, and press this button for 5 times continuously to reset the mainboard.

For more information about the front panel and relevant operations, see 3. Front panel operation.

2.2.2. LOWER HOUSING

The lower housing contains one SIM card slot, two battery compartments, one TNC radio antenna connector, two communication and power ports, one 5/8-11 threaded insert, and two nameplates.

2.2.3. RECEIVER PORTS
## 2. Getting started with i70

### 2.3. BATTERIES AND POWER

#### 2.3.1. INTERNAL BATTERIES

The receiver has two rechargeable Lithium-ion batteries, which can be removed for charging.

##### 2.3.1.1. Charging the battery

The rechargeable Lithium-ion battery is supplied partially charged. Charge the battery completely before using it for the first time. To charge the battery, first remove the battery from the receiver, and then place it in the battery charger, which is connected to AC power.

**WARNING** - Charge and use the rechargeable Lithium-ion battery only in strict accordance with the instructions. Charging or using the battery in unauthorized equipment can cause an explosion or fire, and can result in personal injury and/or equipment damage.

To prevent injury or damage:

- Do not charge or use the battery if it appears to be damaged or leaking.
- Charge the Lithium-ion battery only in a CHC product that is specified to charge it. Be sure to follow all instructions that are provided with the battery charger.
- Discontinue charging a battery that gives off extreme heat or a burning odor.
- Use the battery only in CHC equipment that is specified to use it.
- Use the battery only for its intended use and according to the instructions in the product documentation.

<table>
<thead>
<tr>
<th>Port</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IO port</td>
<td>This port is a 7-pin Lemo connector that supports RS-232 communications and external power input. Users can use GPS to PC Data Cable supplied with the system to realize RS-232 communications between the receiver and computer or controller. Also, users can use a 7-pin cable to transmit differential data to an external radio.</td>
<td></td>
</tr>
<tr>
<td>USB port</td>
<td>This port is a mini-USB connector that supports USB communications. Users can use USB Cable supplied with the system to download the logged data to a computer.</td>
<td></td>
</tr>
<tr>
<td>Radio antenna connector</td>
<td>Connect a radio antenna to internal radio of the receiver. And this connector is not used if you are using an external radio.</td>
<td></td>
</tr>
</tbody>
</table>
2.3.1.2. Battery safe

WARNING - Do not damage the rechargeable Lithium-ion battery. A damaged battery can cause an explosion or fire, and can result in personal injury and/or property damage.

To prevent injury or damage:

- Do not use or charge the battery if it appears to be damaged. Signs of damage include, but are not limited to, discoloration, warping, and leaking battery fluid.
- Do not expose the battery to fire, high temperature, or direct sunlight.
- Do not immerse the battery in water.
- Do not use or store the battery inside a vehicle under hot weather condition.
- Do not drop or puncture the battery.
- Do not open the battery or short-circuit its contacts.

WARNING - Avoid contact with the rechargeable Lithium-ion battery if it appears to be leaking. Battery fluid is corrosive, and contact with it can result in personal injury and/or property damage.

To prevent injury or damage:

- If the battery leaks, avoid the battery fluid.
- If battery fluid gets into your eyes, immediately rinse your eyes with clean water and seek medical attention. Please do not rub your eyes!
- If battery fluid gets onto your skin or clothing, immediately use clean water to wash off the battery fluid.

2.3.2. EXTERNAL POWER SUPPLY

Two methods are available for providing the external power to the receiver by the GPS to PC Data Cable+ Power Adapter, or GPS to PC Data Cable + external power cable (option purchase)+ vehicle battery.

In the office:

The Power Adapter is connecting with AC power of 100-240V, the output port of the Power Adapter connects with the Power Port of the GPS to PC Data Cable.
In the field:

The external power cable is connecting with a vehicle battery, the output port of the external power cable connects with the Power Port of the GPS to PC Data Cable.

WARNING - Use caution when connecting external power cable’s clip leads to a vehicle battery. Do not allow any metal object to connect (short) the battery’s positive (+) terminal to either the negative (-) terminal or the metal part of the vehicle battery. This could result in high current, arcing, and high temperatures, exposing the user to possible injury.

2.4. INSERTING BATTERY AND SIM CARD

Push down the spring-loaded button on the battery cover to open the cover.

Make electrode sheets of battery turn toward the receiver, align the socket of the battery and the lug of the battery compartment, and then insert the battery into the battery compartment until it is locked by the battery bail.

To remove the battery, slide the battery bail to the left or right.
2. Getting started with i70

Insert the SIM card with the contacts facing upward, as indicated by the SIM card icon next to the SIM card slot.

To eject the SIM card, slightly push it in to trigger the spring-loaded release mechanism.

Tip – The SIM card is provided by your cellular network service provider.

2.5. PRODUCT BASIC SUPPLY ACCESSORIES

2.5.1. BASE KIT BASIC SUPPLY

<table>
<thead>
<tr>
<th>Item</th>
<th>Picture</th>
</tr>
</thead>
<tbody>
<tr>
<td>i70 GNSS Receiver</td>
<td><img src="image1.png" alt="i70 GNSS Receiver" /></td>
</tr>
<tr>
<td>UHF Bar Antenna (450-470 MHz)</td>
<td><img src="image2.png" alt="UHF Bar Antenna" /></td>
</tr>
<tr>
<td>USB Cable</td>
<td><img src="image3.png" alt="USB Cable" /></td>
</tr>
</tbody>
</table>
## 2. GETTING STARTED WITH i70

### 2.5.2. ROVER KIT BASIC SUPPLY

<table>
<thead>
<tr>
<th>Item</th>
<th>Picture</th>
</tr>
</thead>
<tbody>
<tr>
<td>i70 GNSS Receiver</td>
<td><img src="image1" alt="i70 GNSS Receiver" /></td>
</tr>
<tr>
<td>UHF Bar Antenna (450-470 MHz)</td>
<td><img src="image2" alt="UHF Bar Antenna" /></td>
</tr>
</tbody>
</table>
2.6. CONNECTING TO AN OFFICE COMPUTER

The receiver can be connected to an office computer for serial data transfer or settings via a GPS to PC Data Cable. Before you connect to the office computer, ensure that the receiver is powered on by internal battery or external power.

The following figure shows how to connect to the computer for serial data transfer or settings:
2.7. CONNECTING TO A CONTROLLER

2.7.1. CONNECTING VIA WI-FI WITH LANDSTAR 7 SOFTWARE

1. Turn on the controller → run LandStar 7 → go to Config main menu → tap Connect.
2. In the Connect screen, select CHC for the Manufacture field, i70 for Device Type field, WIFI for Connection Type field,
3. Tap the Wireless Lan icon on the right side to select the hot-spot → Switch on the WiFi module by the top switch → tap refresh button to search the hot spot around → select the target device in the list.
4. Tap **Connect** to link to the hot spot. If the first time connection to this hot spot, user may type in the password.

Tip – **The Wi-Fi key of the receiver is 12345678 by default.**

5. Tap the **Connect** button to build the connection.
2.7.2. CONNECTING VIA BLUETOOTH WITH LANDSTAR 7 SOFTWARE

1. Turn on the controller → run LandStar 7 → go to Config main menu → tap Connect.
2. In the Connect screen, select CHC for the Manufacture field, i70 for Device Type field, Bluetooth for Connection Type field.
3. Tap the Bluetooth Manager and turn on the Bluetooth function to search bluetooth device around → select the target device in the list.
4. Tap **Pair** to connect the bluetooth device → selected the target device in the bluetooth manager list.

5. Tap the **Connect** button to build the connection.
2.8. Downloading Logged Data

Data logging involves the collection of GNSS measurement data over a period of time at a static point or points, and subsequent postprocessing of the information to accurately compute baseline information. Data logging using receivers requires access to suitable GNSS postprocessing software such as the CHC Geomatics Office (CGO) Software.

The procedures of downloading logged data in the receiver are as follows:

1. Switch on the receiver and connect it with a computer by USB Cable. After the successful connection, a removable disk named as the Serial Number (SN) of the receiver will appear on the computer.
2. Double click the removable disk and you will see the folder named as “repo”. Double click this folder, you will see 9 folders. The “push_log” folder is used to save the log files, and the other 8 folders represent different logging session and are used for store static data.
3. Double click the folder that you has configured to store the static data, you will see the folder(s) created by the i70 system automatically and named by the date which is decide by GPS time when you start to log data.
4. Select the destination folder and double click it, and then two folders named as different data format (hcn and rinex) will be displayed.
5. Select the data format that you has configured to save the static data, you will find the static raw data.
Tip – For hcn files, the name of the file is represented as XXXXXDDDNN, where XXXXX is the SN of the receiver, DDD is day of year, and NN is the recording session.

WARNING – The static data will be saved in the first logging session, the “record_1” folder, by default. Old files will be deleted if the storage space is full. If you configure not to auto delete old files when the memory is low, the receiver will stop data logging.
3. FRONT PANEL OPERATION

The front panel contains one LCD screen, two indicator LEDs, and two buttons. The operating controls are all located on the front panel.

3.1. MAIN OPERATION MENUS

The main operation menus of the front panel are as follows:

<table>
<thead>
<tr>
<th>Top-level Menu</th>
<th>Second-level Menu</th>
<th>Description</th>
</tr>
</thead>
</table>
|                | SV: 22 Battery: 97% | • Click *Enter* button to enter the second-level menus.  
• Indicates the number of the satellites tracked and the internal batteries power remaining.  
• If the receiver is searching for satellites and the batteries are not be inserted, this menu will be displayed as “SV: Getting Battery: N/A”. |
|                | 22 = G09 R05 C07 S00 E0 | Indicates the total number of satellites that have been tracked and the number of satellites tracked of each constellation, where G represents GPS, R represents GLONASS, C represents BeiDou, S represents SBAS and E represents Galileo. |
|                | Pwr: A 97% B 97% | Indicates the remaining power of the battery inserted in the left (B) and right (A) battery compartment. |
|                | Wlan Status On Wlan Mode HotSpot | • Indicates the Wi-Fi status.  
• Click *Enter* button to change the status, and then click *Fn* button to cancel the change, or click *Enter* button to confirm the change. |
|                | Dial Status Offline | • Indicates whether the receiver has been connected to cellular network.  
• Generally, when the SIM card has been inserted before the receiver is turned on, this menu will be displayed as “Dial Status Online”. |
|                | Cancel | Click *Enter* button to back to the top-level menu. |
### Mode Rover UHF

- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Base Cable**
- Click **Enter** button to enter the configuration screen of the selected working mode.
- More operation information, see 3.2. **Configure the working mode**.

**Base Int. UHF**
- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Base API**
- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Base API & Cable**
- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Rover API**
- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Rover Ntrip/IP**
- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Rover UHF**
- Click **Enter** button to enter the second-level menus.
- Indicates the current working mode.

**Cancel**
- Click **Enter** button to back to the top-level menu.

### Static Off

- Click **Enter** button to enter the second-level menus.
- Indicates the current data logging status: Static Off or Static On.

### Set Off

- Click **Enter** button to change the data logging status.

**Recorded 00:02**
- Indicates the duration of data logging.

**Epoch Intv 1s**
- Click **Enter** button to change the measurement interval.
- The available options are: 0.2s, 0.5s, 1s, 2s, 5s, 10s, 15s, 30s, and 60s.

### Mask Angle 13 Degree

- Click **Enter** button to change the mask degree from 0 degree to 15 degrees.

### Duration time 1440 min

- Click **Enter** button to enter **Duration Time Setting** screen.
- In the **Duration Time Setting** screen, click **Fn** button to move to the character of the duration time value you want to make change, and then click **Enter** button to change from 0 to 9. After the change has been done, you can click **Fn** button to move to **OK** field, and then click **Enter** button to save the change and back to the second-level menu; or click **Fn** button to move to **Cancel** field and click **Enter** button to cancel the change and back to the second-level menu.

### OK

- Click **Enter** button to save the settings of the data logging and back to the top-level menu, and then the settings will take effect.
3. Front panel operation

Cancel

Click Enter button to cancel the settings of the data logging and back to the top-level menu.

Receiver Info.

Click Enter button to enter the second-level menus and check the basic information about the receiver.

SN 1000514

Displays the Serial Number (SN) of the receiver.

PN 1180020032231

Displays the Part Number (PN) of the receiver.

Reg. 20301231

Displays the expiry date of registration code.

Ver. 1.1.41

Displays the firmware version.

Language English

Click Enter button to change the display language between Chinese, English and Russian.

Cancel

Click Enter button to back to the top-level menu.

3.2. CONFIGURE THE WORKING MODE

7 working modes are provided for quickly setting up a RTK base station or rover station. Users can configure each working mode through front panel as follows:

<table>
<thead>
<tr>
<th>Working Mode</th>
<th>Menus in Configuration Screen</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Base Cable</td>
<td></td>
<td>• Set up the receiver as a base station using external UHF.</td>
</tr>
<tr>
<td></td>
<td>Mode Base Cable</td>
<td>The title of this configuration screen.</td>
</tr>
<tr>
<td></td>
<td>Format CMR</td>
<td>• Click Enter button to change the correction format.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• The available correction formats are: CMR, CMR+, RTCMv2.1, RTCMv2.2, RTCM v2.3, RTCM v3.0, and RTCM v3.2.</td>
</tr>
<tr>
<td></td>
<td>OK</td>
<td>Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect.</td>
</tr>
<tr>
<td></td>
<td>Cancel</td>
<td>Click Enter button to cancel the settings and back to the second-level menu.</td>
</tr>
<tr>
<td>Base Int. UHF</td>
<td></td>
<td>• Set up the receiver as a base station using internal UHF.</td>
</tr>
<tr>
<td></td>
<td>Mode Base Int. UHF</td>
<td>The title of this configuration screen.</td>
</tr>
</tbody>
</table>

### Front panel operation

<table>
<thead>
<tr>
<th>Feature</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Channel 1</strong></td>
<td>Click Enter button to change the channel from 1 to 9.</td>
</tr>
</tbody>
</table>
| **Format CMR**   | - Click Enter button to change the correction format.  
                  - The available correction formats are: CMR, CMR+, RTCM v2.3, RTCM v3.0, and RTCM v3.2. |
| **Power 2w**     | - Click Enter button to change the transmitting power.  
                  - The available transmitting power options are: 0.1w, 0.5w, 1w and 2w. |
| **Protocol CHC** | Indicates the current protocol. |
| **OK**           | Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect. |
| **Cancel**       | Click Enter button to cancel the settings and back to the second-level menu. |

**Base APIS**

- Set up the receiver as a base station using APIS service.
- Click Enter button to enter the configuration screen.

**Mode Base APIS**

- Click Enter button to change the correction format.
- The available correction formats are: CMR, CMR+, RTCM v2.3, RTCM v3.0, and RTCM v3.2.

**IP 211.144.118.5**

- Click Enter button to enter Common IP screen.
- In Common IP screen, click Fn button to move to the line of IP address, and then click Enter button to change to other predefined IP address. After the IP address has been changed, you can click Fn button to move to OK field, and then click Enter button to save the change and back to the second-level menu; or click Fn button to move to Cancel field and click Enter button to cancel the change and back to the second-level menu.

**Port 9901**

- Click Enter button to change the port from 9901.
3. Front panel operation

**OK**
Click **Enter** button to save the settings and back to the top-level menu, and then this combination working mode will take effect.

**Cancel**
Click **Enter** button to cancel the settings and back to the second-level menu.

**Base APIS & Cable**
- Set up the receiver as a base station using both APIS service and external UHF.
- Click **Enter** button to enter the configuration screen.

**Format CMR**
- Click **Enter** button to change the correction format.
- The available correction formats are: CMR, CMR+, RTCM v2.3, RTCM v3.0, and RTCM v3.2.

**IP 211.144.118.5**
- Click **Enter** button to enter **Common IP** screen.
- In **Common IP** screen, click **Fn** button to move to the line of IP address, and then click **Enter** button to change to other predefined IP address. After the IP address has been changed, you can click **Fn** button to move to **OK** field, and then click **Enter** button to save the change and back to the second-level menu; or click **Fn** button to move to **Cancel** field and click **Enter** button to cancel the change and back to the second-level menu.

**Port 9901**
Click **Enter** button to change the port from 9901 to 9920.

**OK**
Click **Enter** button to save the settings and back to the top-level menu, and then this combination working mode will take effect.

**Cancel**
Click **Enter** button to cancel the settings and back to the second-level menu.

**Rover APIS**
- Set up the receiver as a rover station using APIS service.
- Click **Enter** button to enter the
3. Front panel operation

<table>
<thead>
<tr>
<th>Configuration Screen</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mode Rover APIS</td>
<td>The title of this configuration screen.</td>
</tr>
<tr>
<td>Current Base SN 1000456</td>
<td>• Display the SN of corresponding base station.</td>
</tr>
<tr>
<td></td>
<td>• Click Enter button to enter <em>Base SN setting</em> screen. In the <em>Base SN setting</em> screen, click Fn button to move to the character of the value you want to make change, and then click Enter button to change from digital 0 to 9 (in addition, the initial character can be changed to letter R). After the change has been done, you can click Fn button to move to OK field, and then click Enter button to save the change and back to the second-level menu; or click Fn button to move to Cancel field and click Enter button to cancel the change and back to the second-level menu.</td>
</tr>
<tr>
<td>IP 211.144.118.5</td>
<td>• Click Enter button to enter <em>Common IP</em> screen.</td>
</tr>
<tr>
<td></td>
<td>• In <em>Common IP</em> screen, click Fn button to move to the line of IP address, and then click Enter button to change to other predefined IP address. After the IP address has been changed, you can click Fn button to move to OK field, and then click Enter button to save the change and back to the second-level menu; or click Fn button to move to Cancel field and click Enter button to cancel the change and back to the second-level menu.</td>
</tr>
<tr>
<td>Port 9901</td>
<td>Click Enter button to change the port from 9901 to 9920.</td>
</tr>
<tr>
<td>OK</td>
<td>Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect.</td>
</tr>
<tr>
<td>Cancel</td>
<td>Click Enter button to cancel the settings and back to the second-level menu.</td>
</tr>
<tr>
<td>Rover Ntrip/IP</td>
<td>• Set up the receiver as a rover station using Ntrip.</td>
</tr>
<tr>
<td></td>
<td>• Click Enter button to enter the configuration screen.</td>
</tr>
</tbody>
</table>
### 3. Front panel operation

<table>
<thead>
<tr>
<th>Mode</th>
<th>Operation</th>
<th>Description</th>
</tr>
</thead>
</table>
| Mode Rover Ntrip/IP | Status Logged | The title of this configuration screen.  
- Indicates current status of Ntrip: Status Not Logged or Status Logged.  
- Users need to use the web interface to configure the settings to log on Ntrip (see 7.5.1. IO Settings submenu → RTK Client for instruction) before.  

**Note** – Make sure a valid SIM card has been inserted in the receiver.

- **OK** Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect.  
- **Cancel** Click Enter button to cancel the settings and back to the second-level menu.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Operation</th>
<th>Description</th>
</tr>
</thead>
</table>
| Mode Rover UHF | Channel 1 | The title of this configuration screen.  
- Click Enter button to change the channel from 1 to 9.  

**Note** – The operation menus of front panel may vary from different firmware versions of your receiver. The menus described in this chapter are based on firmware version 1.1.41.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Operation</th>
<th>Description</th>
</tr>
</thead>
</table>
| Mode Rover UHF | Protocol CHC | Indicates the current protocol.  
- Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect.  

- **OK** Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect.  
- **Cancel** Click Enter button to cancel the settings and back to the second-level menu.

- **Note** – Make sure a valid SIM card has been inserted in the receiver.

**OK** Click Enter button to save the settings and back to the top-level menu, and then this working mode will take effect.  

- **Cancel** Click Enter button to cancel the settings and back to the second-level menu.
4. BASE STATION SETUP AND OPERATION

Real-Time Kinematic (RTK) operation provides centimeter-level precision by eliminating errors that are present in the GNSS system. For all RTK operations, you require both a rover receiver and a source of corrections from a base station or network of base stations.

A base station consists of a receiver that is placed at a known point. The receiver tracks the same satellites that are being tracked by the rover receiver simultaneously. Errors in the GNSS system are monitored at the base station, and a series of position corrections are computed. The messages are sent through a radio link to the rover receiver, where they are used to correct the real time positions of the rover.

This chapter provides the information to help you identify good setup locations, outlines basic precautions that you need to take to protect the equipment, and describes the conventional process to set up the base station and the configuring procedure that required for transmitting correction data.

4.1. BASE STATION SETUP GUIDELINES

For good performance, the following base station setup guidelines are recommended:

- Place the GNSS receiver in a location on the worksite where equal range in all directions provides full coverage of the site.
- Place the GNSS antenna in a location that has a clear line of sight to the sky in all directions. Do not place the antenna near vertical obstructions such as buildings, deep cuttings, site vehicles, towers, or tree canopy.
- The GNSS antenna must have a clear line of sight to the sky at all times during operation.
- Place the GNSS and radio antennas as high as practical. This minimizes multipath from the surrounding area, and enables the radio to broadcast to the maximum distance.
- Choose the most appropriate radio antenna for the size of the worksite. The higher the gain on the antenna, the longer the range.
- Make sure that the GNSS receiver does not lose power. To operate continuously for more than a few hours without loss of power at the base station, provide external power. When you use an external power supply, the integrated battery provides a backup power supply, enabling you to maintain continuous operation through a mains power failure.
- Do not locate a GNSS receiver, GNSS antenna, or radio antenna within 400 meters (about 1,300 feet) of transmitters, such as a power radar or
cellular communications tower.

- Do not set up the base station close to the sources of electromagnetic interference, include alternators and generators, electric motors, equipment with DC-to-AC converters, etc.
- Do not operate the receiver outside the specified operating temperature range -40°C to +60°C (-40°F to +140°F).
- Take reasonable care to keep the GNSS receiver equipment dry, which could prolong their life and reduce the effects of corrosion on ports and connectors.

4. Outputting corrections using internal radio modem

4.2. Base station setup

4.2.1. Base station setup

1. Connect the radio antenna onto i70 receiver. Screw the receiver onto extension pole.
2. Screw the extension pole with auxiliary H.I. tool onto tribrach adaptor.
3. Mount the tribrach onto the tripod.
4. Insert the tribrach adaptor into the tribrach.
5. Level and plumb the receiver over the known (control) point.
6. Measure the height of the base station GNSS antenna by measuring the slant height from the known (control) point to the end of auxiliary H.I. tool. 

*Note – After entered the vertical height from the known (control) point to the bottom of receiver that you calculated by adding the height of the extension pole to the height from the known (control) point to the auxiliary H.I. tool, LandStar 7 will calculate the height to the Antenna Phase Center (APC) automatically.*

7. If required, connect the receiver to an external 12 V power supply.
4. Base station setup and operation

4.3. OUTPUTTING CORRECTIONS USING EXTERNAL RADIO

For base receiver part:

1. Screw the i70 receiver onto extension pole.
2. Screw the extension pole with auxiliary H.I. tool onto tribrach adaptor.
3. Mount the tribrach onto the tripod.
4. Insert the tribrach adaptor into the tribrach.
5. Level and plumb the receiver over the known (control) point.
6. Measure the height of the base station GNSS antenna by measuring the slant height from the known (control) point to the auxiliary H.I. tool.

Note – After entered the vertical height from the known (control) point to the bottom of receiver that you calculated by adding the height of the extension pole to the height from the known (control) point to the end of auxiliary H.I. tool, LandStar 7 will calculate the height to the Antenna Phase Center (APC) automatically.

7. If required, connect the receiver to an external 12 V power supply.

For external radio part (take the CHC DL6 Datalink for example):

8. Connect the Datalink Antenna to the 3 meter Cable for Datalink Antenna.
9. Connect 3 meter Cable for Datalink Antenna to Datalink Antenna Mounting Pole.
10. Screw the Datalink Antenna Mounting Pole onto the tribrach adapter.
11. Mount the tribrach onto the tripod.
12. Insert the tribrach adaptor into the tribrach.
13. Set up the Datalink Antenna nearby the base receiver.
14. Fix the DL6 Datalink onto the tripod.
15. Place the car battery at an appropriate location.

For connection between the receiver part and external radio part:

16. Connect Datalink Antenna to the Datalink Antenna Slot of DL6 Datalink via 3 meter Cable for Datalink Antenna.
17. Connect the base receiver with DL6 Datalink via GPS to Datalink Cable.
18. Connect the car battery with DL6 Datalink via Datalink External Power Cable.

CAUTION – The Datalink Antenna must be connected to the Datalink before the Datalink is powered on; otherwise, the Datalink can be damaged.
5. ROVER STATION SETUP AND OPERATION

Real-Time Kinematic (RTK) operation provides centimeter-level precision by eliminating errors that are present in the GNSS system. For all RTK operations, you require both a rover receiver and a source of corrections from a base station or network of base stations.

The second part of the RTK GNSS system is the rover receiver. The rover receiver is moved between the points that require measurement or stakeout. The rover receiver is connected to a base station or to a source of RTK corrections such as a CORS (Continuous Operational Reference System) or the CHC APIS service. The connection is provided by:

- an integrated radio
- an integrated cellular modem
- a cellular modem in the controller

This chapter provides the information to help you identify good setup locations, describes the conventional process to set up the rover station and the configuring procedure that required for receiving correction data.

5.1. ROVER STATION SETUP GUIDELINES

For good rover operation, observe the following setup guidelines:

- Place the GNSS antenna in a location that has a clear line of sight to the sky in all directions. Do not place the antenna near vertical obstructions such as buildings, deep cuttings, site vehicles, towers, or tree canopy. GNSS rovers and the base station receive the same satellite signals from the same satellites. The system needs five common satellites to provide RTK positioning.

WARNING – Take care not to touch overhead power lines with the CHC i70 GNSS receiver or the range pole when moving the equipment into position. Touching overhead power lines may cause electrocution, leading to serious injury.

- GNSS satellites are constantly moving. Because you cannot measure at a specific location now does not mean that you will not be able to measure there later, when satellite coverage at the location improves.
- To get a fixed position solution with centimeter precision, initialize the RTK rover receiver. For initialization to take place, the receiver must track at least five satellites that the base station is also tracking. In a dual-satellite constellation operation, for example, GPS and GLONASS, the receiver must track at least six satellites.
To continue to survey at centimeter precisions, the rover must continuously track at least four satellites that the base station is also tracking. The radio link between the base and rover receivers must also be maintained.

Loss of the satellite signals will result in a loss of centimeter position precision.

5.2. ROVER STATION SETUP

1. If required, connect the radio antenna onto i70 receiver.
2. Screw the receiver on top of the range pole.
3. Fix the controller bracket on the range pole.
4. Fit the controller in the controller bracket.
5. Level and plumb the receiver over the target measuring point.
6. CONFIGURING THROUGH A WEB BROWSER

Supported browsers:

- Google Chrome
- Microsoft Internet Explorer® version 10, or higher

To connect to the receiver through a web browser:

1. Turn on the Wi-Fi of the receiver.
2. Search the wireless network named as GNSS-XXXXXXX (the SN of your receiver) on your computer, and then establish the connection.
3. After the successful connection between your computer and the receiver, enter the IP address of the receiver into the address bar of the web browser on your computer:

4. The web browser prompts you to enter a login account and password:

![Login Screen]

The default login account for the receiver is:

- Login Account: admin
- Password: password

Note – Tick remember me option, and then the browser will remember the Login Account and Password you entered for the next time you enter this login screen.

5. Once you are logged in, the web page appears as follows:
This web page shows the configuration menus on the left of the browser window, and the setting on the right. Each configuration menu contains the related submenus to configure the receiver and monitor receiver performance.

This chapter describes each configuration menu.

To view the web page in another language, select the corresponding language name from the dropdown list on the upper right corner of the web page.

Currently, three languages are available:

- English
- 中文
- Русский язык

### 6.1. Status Menu

This menu provides a quick link to review the receiver’s position information, satellites tracked, runtime, current data log status, current outputs, available memory, and more.

#### 6.1.1. Position Submenu

This page shows the relevant position information about the receiver’s
position solution which including the position, DOP values, satellites used and tracked, and the receiver clock information.

<table>
<thead>
<tr>
<th>Position</th>
<th>DOP</th>
</tr>
</thead>
<tbody>
<tr>
<td>Latitudes: 31°55'58.720&quot;N (Equator)</td>
<td>FDOP: 1.022000</td>
</tr>
<tr>
<td>Longitudes: 121°17'19.974&quot;W (Prime)</td>
<td>HDOP: 0.992000</td>
</tr>
<tr>
<td>Height: 28.304</td>
<td>TDOP: 1.017000</td>
</tr>
<tr>
<td>Type: 3D</td>
<td>PDOP: 0.713000</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Satellite Status</th>
<th>PRN</th>
<th>GPS/IONA/IRN/SAA/GBAS</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPS/BDS</td>
<td>1.7 9.3 11.10.27.30</td>
<td>SLC/NAV/IRN/SAA/GBAS</td>
</tr>
<tr>
<td>GLONASS/Galileo</td>
<td>9.10.11.15.20.21</td>
<td>1.2 3.7 4.10.10</td>
</tr>
<tr>
<td>QZSS</td>
<td>1.2 3.7 4.10.10</td>
<td>1.2 3.7 4.10.10</td>
</tr>
<tr>
<td>BGRS</td>
<td>1.2 3.7 4.10.10</td>
<td>1.2 3.7 4.10.10</td>
</tr>
</tbody>
</table>

**6.1.2. Activity Submenu**

Lists several important items to help you understand how the receiver is being used and its current operating condition. Items include the identities of currently tracked satellites, internal and external storage usage rate, how long the receiver has been operational, state of the internal battery, power source state, files being logged, and data streams being output. With this information, it is easy to tell exactly what functions the receiver is performing:

**Activity**

<table>
<thead>
<tr>
<th>Satellite Status</th>
<th>PRN</th>
<th>GPS/IONA/IRN/SAA/GBAS</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPS/BDS</td>
<td>1.7 9.3 11.10.27.30</td>
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<tr>
<td>BGRS</td>
<td>1.2 3.7 4.10.10</td>
<td>1.2 3.7 4.10.10</td>
</tr>
</tbody>
</table>

**Activity Status**

- Current Time: 2017-05-11 07:02:40 (UTC)
- Operational Status: Normal
- Internal Storage: 3.02GB of 36.94GB
- External Storage: 5%
- External Power: Connected
- Battery A: 100%
- Battery B: 90%

**Data Logging**

- Recording Mode: Continuous
- File Name: Base
- Internally: Yes/No
- Log Status: Active/Inactive

**Data Export**

- Format: ASCII
- Output Data: Yes/No
- 1: WKB Data
- 2: FDCM/ERF Data
- 3: FDCM/ERF Data
- 4: FDCM/ERF Data
- 5: FDCM/ERF Data
- 6: FDCM/ERF Data
- 7: FDCM/ERF Data
- 8: FDCM/ERF Data
- 9: FDCM/ERF Data
- 10: FDCM/ERF Data
- 11: FDCM/ERF Data
- 12: FDCM/ERF Data
- 13: FDCM/ERF Data
- 14: FDCM/ERF Data
- 15: FDCM/ERF Data
- 16: FDCM/ERF Data
- 17: FDCM/ERF Data
- 18: FDCM/ERF Data
- 19: FDCM/ERF Data
- 20: FDCM/ERF Data
6.1.3. GOOGLE MAP SUBMENU

Tap this submenu to show the location of the receiver on Google map.

6.2. SATELLITES MENU

Use the Satellites menu to view satellite tracking details and enable/disable GPS, SBAS, GLONASS, BDS and Galileo constellations. These menus include tabular and graphical displays to provide all required information on satellite tracking status.

6.2.1. TRACKING TABLE SUBMENU

Provides the status of satellites tracked in general, such as the satellite ID, satellite type, attitude angle, azimuth angle, L1 SNR, L2 SNR, L5 SNR and enable/disable status of each one.
6.2.2. Tracking Info. Table Submenu

The following figure is an example of satellite track diagram page. Users can determine the satellite types and the corresponding SNR of L-band carriers to be displayed in any combination.

![Satellite Track Diagram](image)

6.2.3. Tracking SkyPlot Submenu

The following figure is an example of Skyplot page.

![Skyplot Diagram](image)

6.2.4. Satellite Activation Submenu

Use this menu to enable or disable satellites.

![Satellite Activation Table](image)
6.3. **RECEIVER CONFIGURATION MENU**

Use this menu to configure settings such as the antenna type and height, elevation mask and PDOP setting, the reference station coordinates, receiver resetting and web interface language:

![Receiver Configuration Menu](image)

6.3.1. **DESCRIPTION**

This submenu shows the receiver information and reference station information, including antenna related information, elevation mask angle, reference station work mode and position, etc.

![Receiver Summary](image)

6.3.2. **ANTENNA CONFIGURATION SUBMENU**

Use this screen to configure all of the items relating to the GNSS antenna. You must enter the correct values for all antenna-related fields, as the choices you make significantly affect the accuracy for logged data and broadcast correction data:

![Antenna Configuration](image)
6.3.3. **REFERENCE STATION SETTINGS SUBMENU**

Use this screen to configure settings such as the station coordinates and the broadcast station identifiers. You must enter accurate information in these fields, as this data significantly affects the accuracy of logged data files and broadcast correction data:
For Reference Station Mode:

There are three modes available:

a) **Auto Rover:** The receiver will serve as a rover after this mode is enabled, and then receive correction data through the working mode set last time.

b) **Auto Base:** The receiver will serve as a base after this mode is enabled, and then broadcast correction data based on coordinate inputted by user, or obtained through autonomous positioning automatically.

c) **Manual Base:** The receiver will serve neither as a base or a rover after this mode is enabled. Users need to configure the receiver manually.

For Reference Latitude and Reference Longitude:

There are mainly three methods to enter the reference coordinates and shown as follows:

a) **Acquire Current Position:** Click this button to acquire current position obtained through autonomous positioning automatically.

b) **Manual Input:** Manually input the coordinate of a control point.

c) **From CORS:** After the receiver logging in CORS, the software can record the coordinate of current position based on fix solution.

For Sample for Average:

Users can determine the positioning limit and sampling amount. The positioning limit falls into two types:

a) **Single Solution Coordinates:** Collect the coordinates of receiver obtained through autonomous positioning.

b) **Fixed Solution Coordinates:** Only collect coordinates of receiver with a fixed solution.

After the configuration of positioning limit and sampling amount, click to carry out sampling and averaging → the progress bar will show the progress → the result will be served as the coordinate of current position.

If users need to save the changes, please tap button.
6.3.4. **RECEIVER RESET SUBMENU**

Use this screen to completely or partially reset the receiver:

![Receiver Reset Screen]

6.3.5. **LANGUAGES SUBMENU**

Use this screen to select the web interface language:

![Language Screen]

6.3.6. **USER MANAGEMENT SUBMENU**

![User Management Screen]

6.3.7. **USB FUNCTION SWITCH SUBMENU**

Use this menu to switch between USB personal area network and Multimedia storage.

![USB Function Switch Screen]

6.3.8. **HCPPP SETTINGS SUBMENU**

Use this menu to select HCPPP Range.

![HCPPP Settings Screen]
6.3.9. 1PPS SUBMENU

Use this button to turn on or turn off 1PPS.

6.4. DATA RECORDING MENU

Use the Data Logging menu to set up the receiver to log static GNSS data and to view the logging settings. You can configure settings such as observable rate, recording rate, continuous logging limit, and whether to auto delete old files if memory is low. This menu also provides the controls for the FTP push feature:

6.4.1. LOG SETTINGS SUBMENU

Here shows the data logging status, including internal and external storage usage and data logging status of each session. Also, users can configure the data logging settings for each session, including recording name, store location, storage limit, store formats, start time, etc.

To edit the settings of each session, click the **Modify** button to the right of the required session, and then the **Recording Edit** screen appears:
7. Configuring through a web browser

Click advanced to see more settings.

In this screen, you can configure all the data logging parameters, and determine whether the recording files will be affected by the FTP Push. The parameters are mainly as follows:

➢ **File Name**: The name of this logging session.
➢ **Sample Interval**: Select the observable rate from the dropdown list.
➢ **Store Location**: Determine whether to store at internal storage or external storage.
➢ **Enable Start Time**: Set the start time of data logging in UTC. Select or not option below to determine whether to start data logging from the start time defined, or immediately after this session is switched on.
➢ **Duration Time**: Set the duration of data logging.
➢ **Assigned Storage**: Set the storage space of this session.
➢ **Circulating Memory**: Select Yes or No option to determine whether to auto delete old files if the storage space is full.
➢ **Data Format**: Set the data format of the logged data.
➢ **FTP Push**: Decide whether to push the stored files to the FTP server of your choice.
7. Configuring through a web browser

Tap ![Save](image) button to save the settings and back to the Log Settings screen. Also, users can click ![Back](image) to abandon the changed settings and back to Log Settings screen.

**Note** – To modify data logging parameters, make sure the data logging session is switched off.

To switch on or off ANY data logging session, tap the ON or OFF button to the right of the required session.

To delete the recorded files of ANY data logging session, tap the Clear button to the right of the required session.

To delete the recorded files of ALL data logging sessions, tap the Clear ALL Accounts button.

6.4.2. FTP PUSH SETTINGS SUBMENU

Use this screen to configure the receiver to push stored files to the FTP server of your choice. Only files that are configured to use FTP push are transmitted.

Tap Modify button to the right of the required FTP server and the FTP Push Settings screen appears:

![FTP Push Settings](image)
6.4.3. FTP Push Log Submenu

Shows the related information about the recorded files that be pushed. And users can tap **Clear Ftp Send Log** button in the upper right corner to clear the log of FTP Push operations.

6.4.4. Data Download Submenu

In this submenu, users can download the data files that recorded in the internal storage through the internal FTP site.

1. Click this submenu, and then the log on dialogue box will prompt you to enter a user name and password:

   ![Authentication Required](image)

   The default logon account for the internal FTP site is:

   - User name: ftp
   - Password: ftp

2. Click the directory named as "repo" to view and download the files currently stored on the receiver:

   ![Index of /](image)

3. To find the file need to be downloaded, click the name of data logging session → the date of file that be recorded → the format of the file → the name of the target file.
To download a file, left-click the name of the target file → download the file according to the prompts.

### 6.5. IO SETTINGS MENU

Use the IO Settings menu to set up all receiver outputs and inputs. The receiver can output CMR, RTCM, Raw data, Ephemeris data, GPGGA, GPGSV, on TCP/IP, UDP, serial port, or Bluetooth ports.

#### 6.5.1. IO SETTINGS SUBMENU

The following figure shows an example of the screen that appears when you select this submenu.

In this submenu, users can configure 6 types of input and output settings.
1. RTK Client

After configuring the settings of RTK client, users can log on CORS or APIS. Tap the **Connect** button to the right → the IO Setting screen will appear → choose one of the connection protocols among the NTRIP, APIS_BASE and APIS_ROVER → configure the related parameters → click **Confirm** to log on CORS or APIS.

➢ **Connection Protocol: NTRIP**

![](image1)

➢ **Connection Protocol: APIS_BASE**

![](image2)

➢ **Connection Protocol: APIS_ROVER**

![](image3)
2. TCP/UDP Client

Tap the Connect button to the right of required TCP/UDP Client → the IO Settings screen will appear → select the connection protocol between TCP and UDP → enter the IP and Port of the target server → configure messages that you want to output to the target server → click to save and complete the connection.

![TCP/UDP Client](image)

3. TCP Server/NTRIP Caster

Tap the Connect button to the right of required TCP Server/NTRIP Caster → the IO Settings screen will appear → select one of the connection protocols between NTRIP and TCP → configure the other related parameters → click to save the settings and open the server.

➢ Connection Protocol: NTRIP

![TCP Server/NTRIP Caster](image)
7. Configuring through a web browser

➢ Connection Protocol: TCP

4. Serial Port

Tap the **Settings** button to the right of Serial Port → the **Serial Port Setup** screen will appear → select Baud Rate used to transmit data → configure the messages that you want to output through the serial port → click ![Confirm](confirm.png) to save the settings and start to transmit.

5. Bluetooth

Tap the **Settings** button to the right of Bluetooth → the **Bluetooth Set** screen will appear → configure the messages that you want to transmit through Bluetooth → click ![Confirm](confirm.png) to save the settings and start to transmit.
6. **Radio**

Tap the **Settings** button to the right of Radio → the **Radio Settings** screen will appear → select the format of differential data that you want to transmit through radio from the dropdown list → click **Confirm** to save the settings and start to transmit.

![Radio Settings](image)

---

### 6.6. **NETWORK SETTING MENU**

Use this menu to view network information, configure the receiver’s mobile network, set email alert for specific situation, configure HTTP or HTTPS port, and the user name and password of internal FTP site:

![Network Setting](image)

#### 6.6.1. **DESCRIPTION SUBMENU**

Use this submenu to check the information of network setting.

![Network Info](image)
6.6.2. **MOBILE NETWORK SETTING SUBMENU**

Use this submenu to configure GPRS model, network module and modify dialing status.

![Mobile Network Setting](image)

6.6.3. **EMAIL ALARM SUBMENU**

Use this submenu to choose which situation of receiver will be alerted and input the email address.

![Email Alert Settings](image)

6.6.4. **HTTP SUBMENU**

Use this submenu to configure HTTP port.

![HTTP](image)
7. Configuring through a web browser

6.6.5. HTTPS SUBMENU

Use this submenu to configure HTTPS port.

![HTTPS Configuration](image)

6.6.6. FTP SERVICE SUBMENU

Use this submenu to configure the user name and password of internal FTP site.

![FTP Settings](image)

6.7. MODULE SETTING MENU

Use this menu to check module information, configure WiFi, bluetooth, radio related settings, and turn on/off static voice of buzzer:

![Module Setting Menu](image)

6.7.1. DESCRIPTION SUBMENU

Use this submenu to check the information of WiFi module, bluetooth module and radio module.
6.7.2. WiFi Submenu

Use this submenu to turn on/off WiFi function and modify password.

6.7.3. Bluetooth Settings Submenu

Use this submenu to turn on/off bluetooth function and modify PIN number.

6.7.4. Radio Settings Submenu

Use this submenu to turn on/off radio function and configure radio parameters.
6.7.5. **BUZZER SETTING SUBMENU**

Use this submenu to turn on/off static voice.

![Buzzer Setting](image)

6.8. **FIRMWARE MENU**

Use this menu to check the current firmware information, download the system log, update the receiver firmware, download or update the configuration file and register the receiver, and more:

![Firmware](image)

6.8.1. **FIRMWARE INFO SUBMENU**

Use this submenu to check the current firmware information. The following figure shows an example of the firmware information.

![Firmware Info.](image)
6.8.2. HARDWARE VERSION

Use this submenu to check the hardware information, including main board version and core board version:

![Hardware Version Table]

6.8.3. CONFIG FILE

Use this submenu to update Configuration File.

![Config File Menu]

6.8.4. SYSTEM LOG DOWNLOAD SUBMENU

Use this submenu to download the system log of the receiver.

![System Log Download]

6.8.5. USER LOG

Use this menu to control the user log.
6.8.6. Firmware Update Submenu

Use this submenu to load new firmware to the receiver across the network. Tap the **Browse** button to locate the upgrade file → tap **Confirm** button to confirm the selected upgrading file and start upgrading.

**Notes**

- *It may take about 3 or 4 minutes to complete the firmware upgrading. Do not touch the power button or unplug the power until the upgrading process is finished, or damage will be caused to the receiver.*
- *The receiver will restart after the firmware upgrading is done, so users need to reconnect the receiver with your computer via Wi-Fi, and then log-in the receiver through a web browser to continue the configuration.*

6.8.7. GNSS Board Upgrade

Use this submenu to upgrade GNSS Board.

6.8.8. Radio Upgrade

Use this submenu to browse upgrade file and upgrade radio.

6.8.9. Upgrade Online

Use this submenu to input Server Address and upgrade online.
7. Configuring through a web browser

6.8.10. GNSS REGISTRATION SUBMENU

Use this submenu to register the receiver. Paste or enter the registration code to the *Registration Code* field → tap **Registration** button to complete the registration.

![GNSS Registration](image)

6.9. CLOUD SERVICE SETTING MENU

6.9.1. CLOUD SERVICE SETTING SUBMENU

Use this submenu to turn on or turn off Cloud Service, **Auto Start**, **Remote Control**, and configure other settings.

![Cloud Service Setting](image)
### A. Communication Ports Definition

#### A.I. CHC i70 Receiver IO Port (7-Pin Lemo Port) Definition

<table>
<thead>
<tr>
<th>PIN</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Ground (-)</td>
</tr>
<tr>
<td>2</td>
<td>Ground (-)</td>
</tr>
<tr>
<td>3</td>
<td>RS232-TX (Output)</td>
</tr>
<tr>
<td>4</td>
<td>PPS</td>
</tr>
<tr>
<td>5</td>
<td>Not Used</td>
</tr>
<tr>
<td>6</td>
<td>VIN</td>
</tr>
<tr>
<td>7</td>
<td>RS232-RX (Input)</td>
</tr>
</tbody>
</table>